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Weather Forecast-Based Optimization of Integrated Energy Systems

*Mihai Anitescu, Argonne National Laboratory
INFORMS San Diego, 2009*

*With Victor Zavala, Emil Constantinescu,
and Ted Krause, Argonne National
Laboratory*

Outline

Objective: Integrative Study of Weather Forecast-Based Optimization

Questions: 1: Can I do a good job in modeling weather uncertainty?

2: Is it worth it (economically)?

Research Problem

Interaction Weather Conditions - Operations

On-Line Stochastic Optimization

Need for Consistent Uncertainty Information

Uncertainty Quantification

Time-Series vs. Physics-Based Models

Case Studies

Photovoltaic-H₂, Building Thermal Control

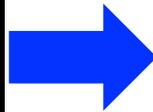
Conclusions and Future Work

Research Problem

Research Problem—Why?

- **Operation of 90% of Energy Systems is Affected by Ambient Conditions**
 - **Power Grid Management:** Predict Demands (*Douglas, et.al. 1999*)
 - **Power Plants:** Production Levels (*General Electric*)
 - **Petrochemical:** Heating and Cooling Utilities (*ExxonMobil*)
 - **Buildings:** Heating and Cooling Needs (*Braun, et.al. 2004*)
 - **Next Generation:** Wind + Solar + Fossil (*Beyer, et.al. 1999*)
- **Efficiency (Waste) Becoming a Major Concern: Focus on management, not only design**

Benefits of Anticipating Weather Conditions?

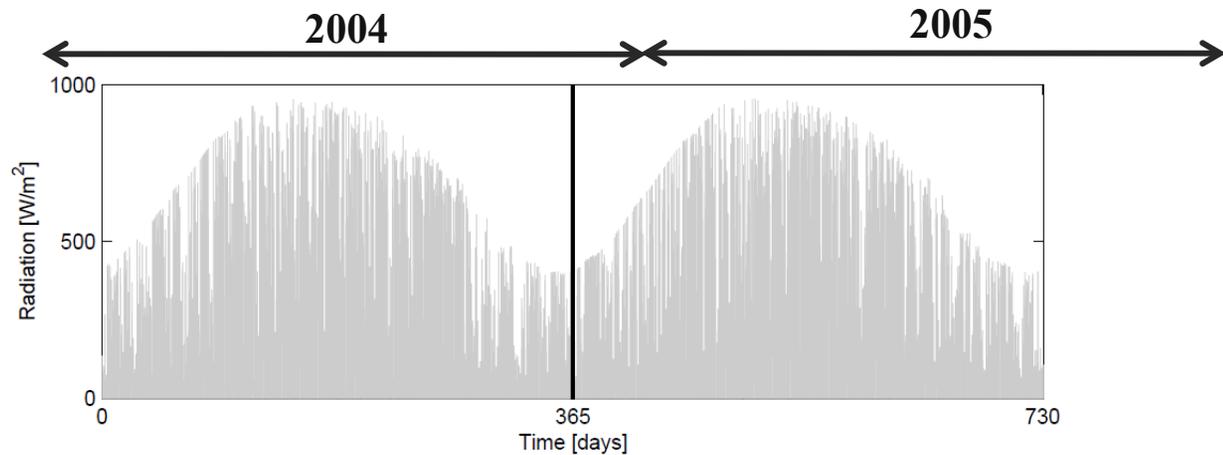


Research Problem

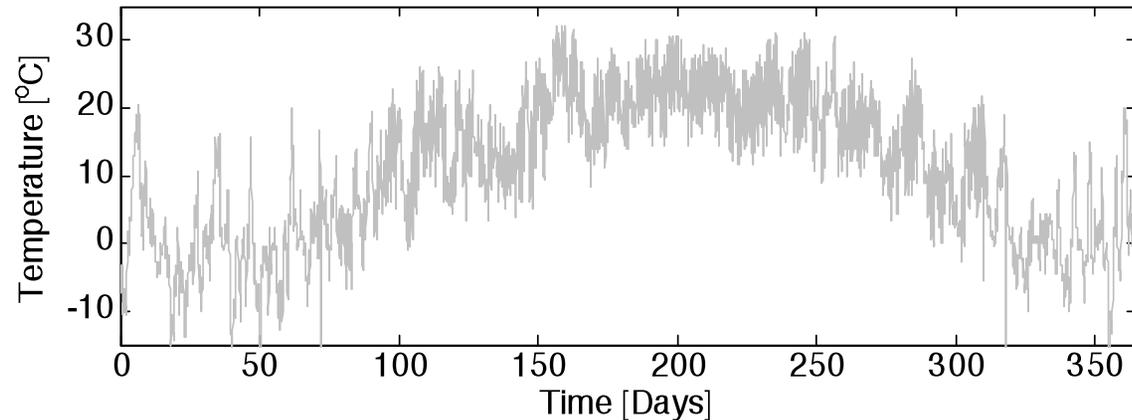
Weather Conditions (Temperature, Radiation, Wind Speed, Humidity ...)

- Complex Physico-Chemical Phenomena, Spatio-Temporal Interactions
- Inherently Periodic (Day-Night, Seasonal)

**Total Ground
Solar Radiation
Chicago, IL**



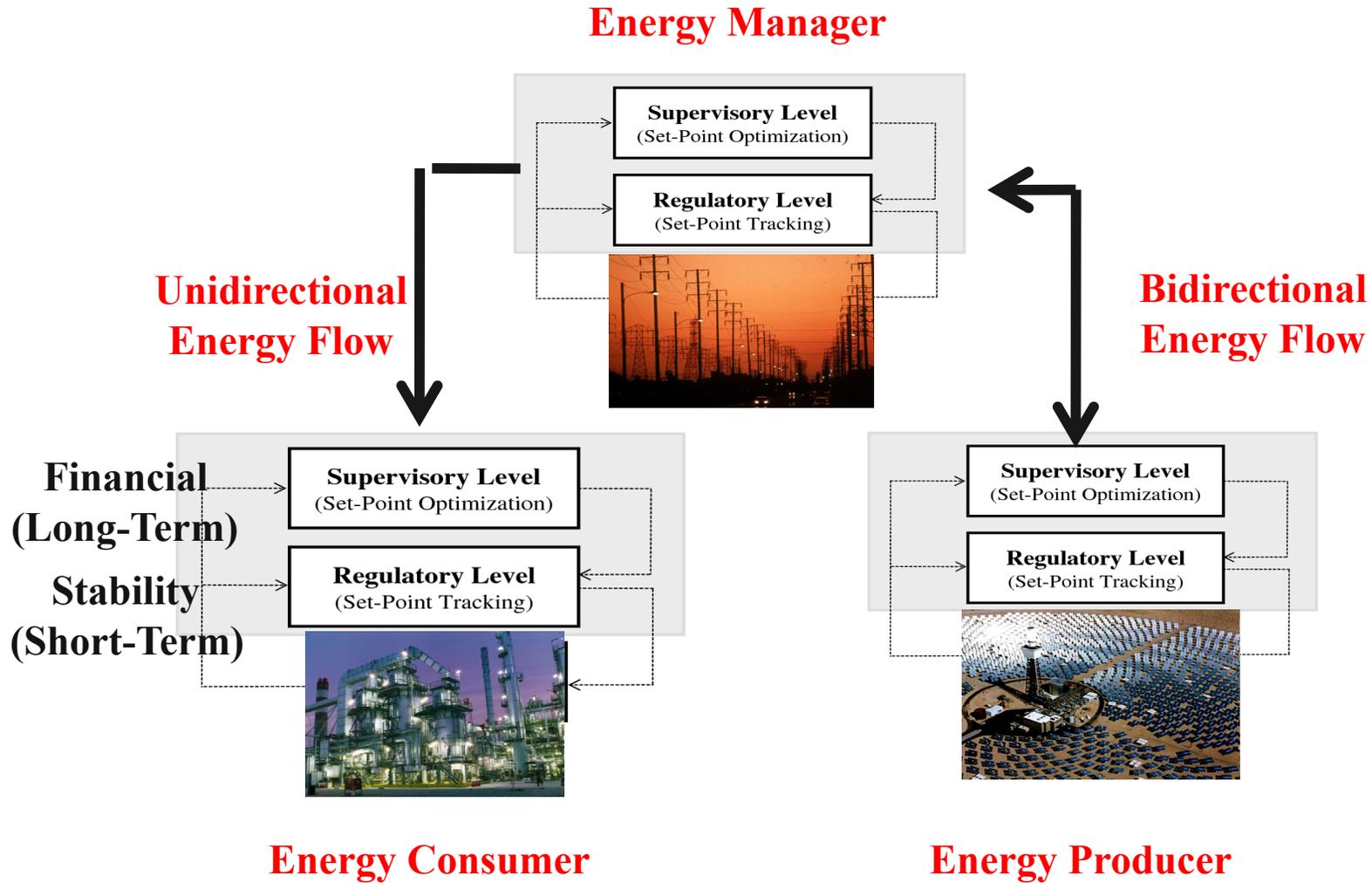
**Ambient Dry-Bulb
Temperature
Pittsburgh, PA**



How to Handle Uncertainty?

On-Line Stochastic Optimization

Hierarchical Operations



Optimization Traditionally Reactive, Uncertainty Handling Non-Systematic

Receding Horizon Optimization

Benefits: Accommodate Forecasts, Constraint Handling, Financial Objectives, Complex Models

Deterministic

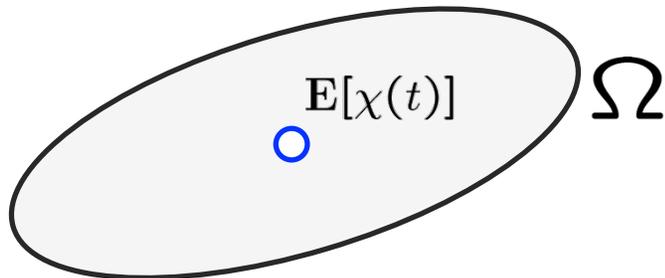
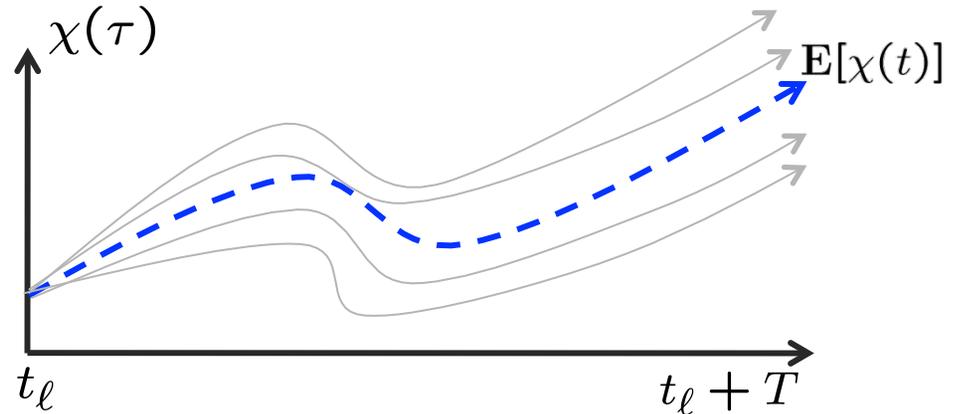
$$\min_{u(t)} \int_{t_\ell}^{t_\ell+N} \varphi(z(t), y(t), u(t), \mathbf{E}[\chi(t)]) dt$$

$$\frac{dz}{dt} = f(z(t), y(t), u(t), \mathbf{E}[\chi(t)])$$

$$0 = g(z(t), y(t), u(t), \mathbf{E}[\chi(t)])$$

$$0 \geq h(z(t), y(t), u(t), \mathbf{E}[\chi(t)])$$

$$z(0) = x_\ell$$

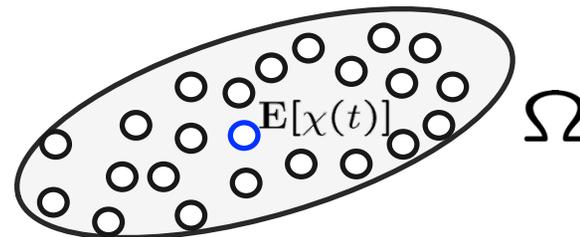


Stochastic

$$\min_{u(t)} \mathbf{E}_{\chi(t) \in \Omega} \left[\int_{t_\ell}^{t_\ell+N} \varphi(z(t), y(t), u(t), \chi(t)) dt \right]$$

$$\left. \begin{aligned} \frac{dz}{dt} &= f(z(t), y(t), u(t), \chi(t)) \\ 0 &= g(z(t), y(t), u(t), \chi(t)) \\ 0 &\geq h(z(t), y(t), u(t), \chi(t)) \end{aligned} \right\} \forall \chi(t) \in \Omega$$

$$z(0) = x_\ell$$



Complexity (Solution Time)

1,000 – 10,000 Differential-Algebraic Equations

100-1000 Scenarios

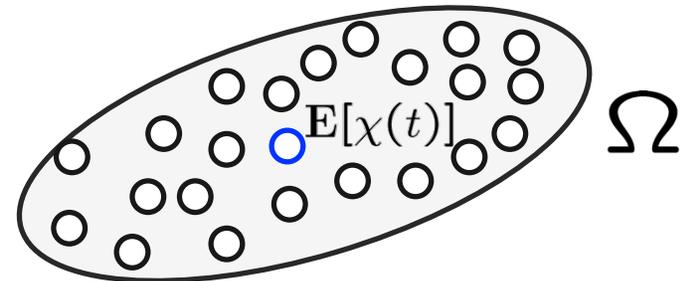
Stochastic Dynamic Optimization

Solution Strategies

- **Dynamic Programming, Taylor Series:** Handling Constraints and Nonlinearity Cumbersome
- **Polynomial Chaos:** Dense Optimization, Multivariable Quadrature
- **Sample Average Approximation (SAA):** Sparse Optimization, Constraints, General Framework

$$\min_{u(t)} \mathbf{E} \left[\int_{t_\ell}^{t_\ell+N} \varphi(z(t), y(t), u(t), \chi(t)) dt \right]$$

$$\left. \begin{aligned} \frac{dz}{dt} &= \mathbf{f}(z(t), y(t), u(t), \chi(t)) \\ 0 &= \mathbf{g}(z(t), y(t), u(t), \chi(t)) \\ 0 &\geq \mathbf{h}(z(t), y(t), u(t), \chi(t)) \\ z(0) &= x_\ell \end{aligned} \right\} \forall \chi(t) \in \Omega$$

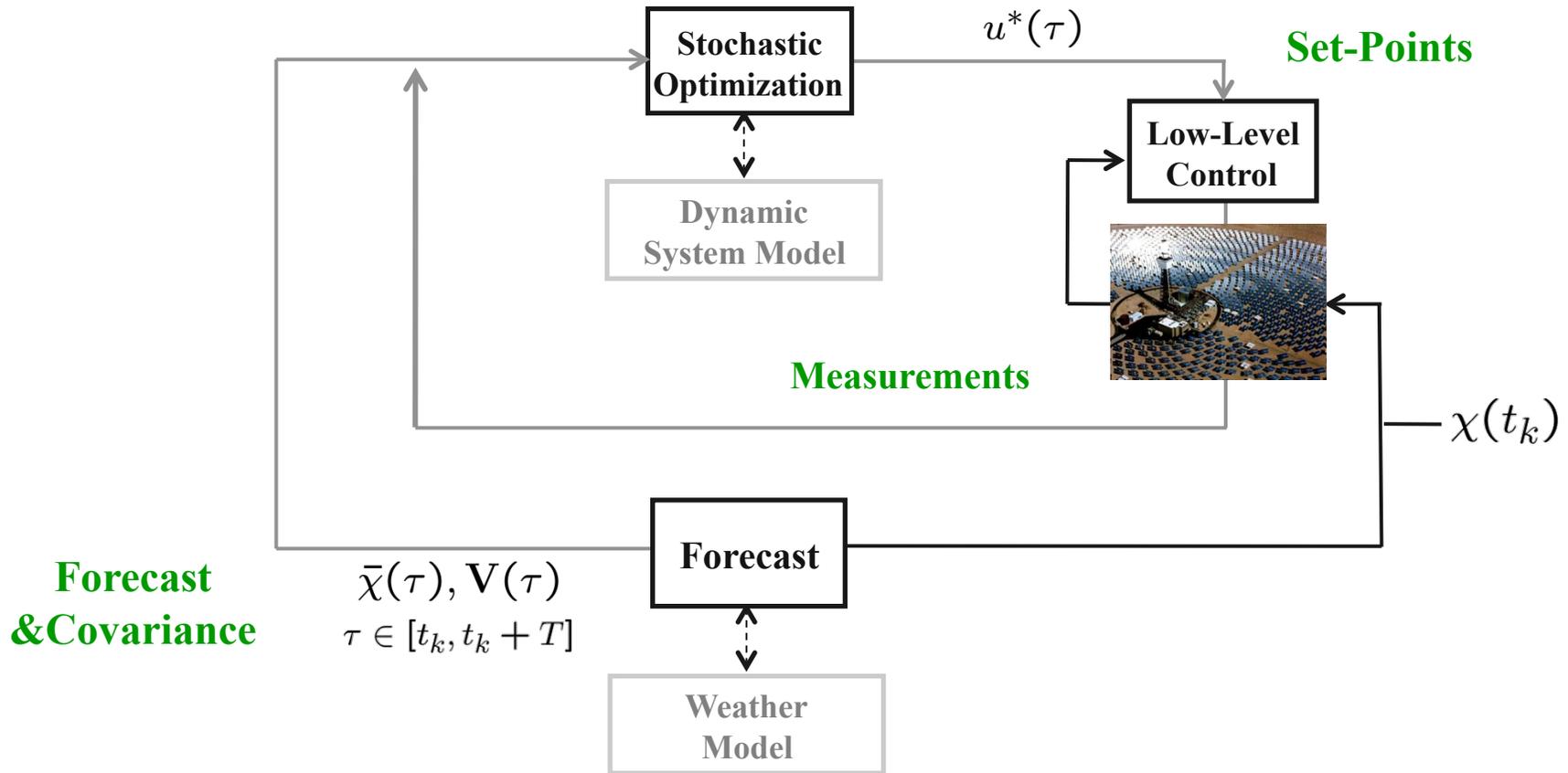


Nonlinear Programming: Exploit Fine and Coarse Structures at Linear Algebra Level

$$\begin{aligned} \min_{\mathbf{u}} \quad & \frac{1}{S} \sum_{k=1}^S \varphi(z_k, y_k, \mathbf{u}, \chi_k) \\ \text{s.t.} \quad & \mathbf{c}(z_k, y_k, \mathbf{u}, \chi_k) = 0 \\ & \mathbf{h}(z_k, y_k, \mathbf{u}, \chi_k) \leq 0 \\ & k = 1, \dots, S \end{aligned}$$

$$\begin{bmatrix} \mathbf{K}_1 & & & Q_1 \\ & \mathbf{K}_2 & & Q_2 \\ & & \dots & \vdots \\ & & & \mathbf{K}_S & Q_S \\ Q_1^T & Q_2^T & \dots & Q_S^T & D_{\mathbf{u}} \end{bmatrix} \begin{bmatrix} \Delta s_1 \\ \Delta s_2 \\ \vdots \\ \Delta s_S \\ \Delta \mathbf{u} \end{bmatrix} = - \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_S \\ r_{\mathbf{u}} \end{bmatrix}$$

Basic Operational Setting



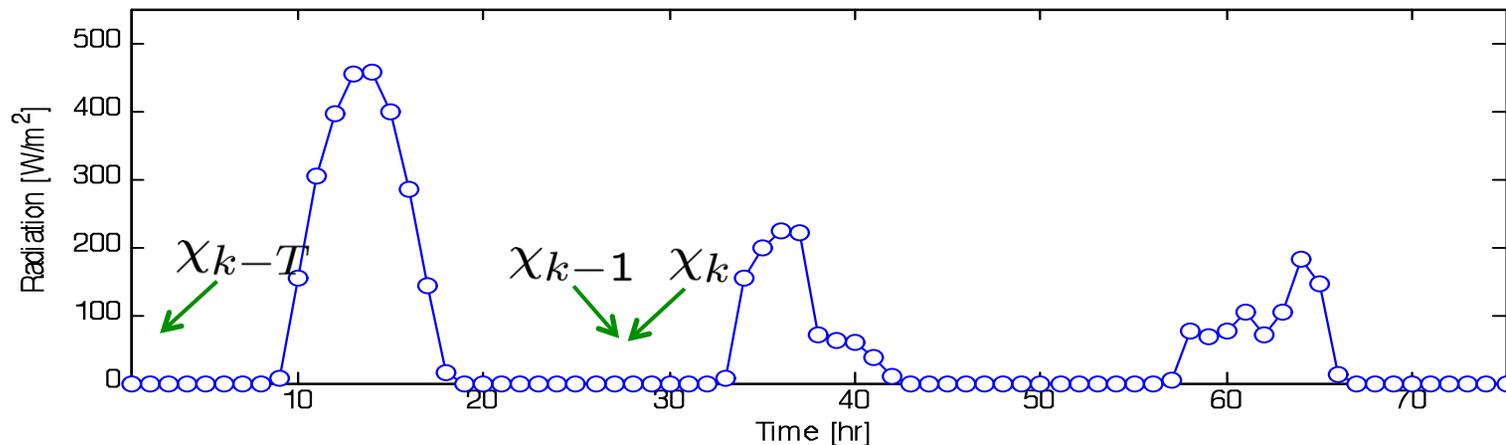
Quantifying Uncertainty Key Enabler

Uncertainty Quantification

Uncertainty Quantification

Quantifying Model Uncertainty (Data-Based (Time-Series) vs. Physics-Based)

Solar Radiation Forecast with Gaussian Process (GP) Modeling *Zavala & A, 2008*



1. **Input-Output Data Sets:** $\mathbf{Y}_j := \chi_k$ $\mathbf{X}_j := [\chi_{k-1}, \chi_{k-T}]$

2. **Covariance Structure :** $V(\mathbf{X}_j, \mathbf{X}_i, \eta) := \eta_0 + \eta_1 \cdot \exp\left(-\frac{1}{\eta_2} \|\mathbf{X}_j - \mathbf{X}_i\|^2\right)$

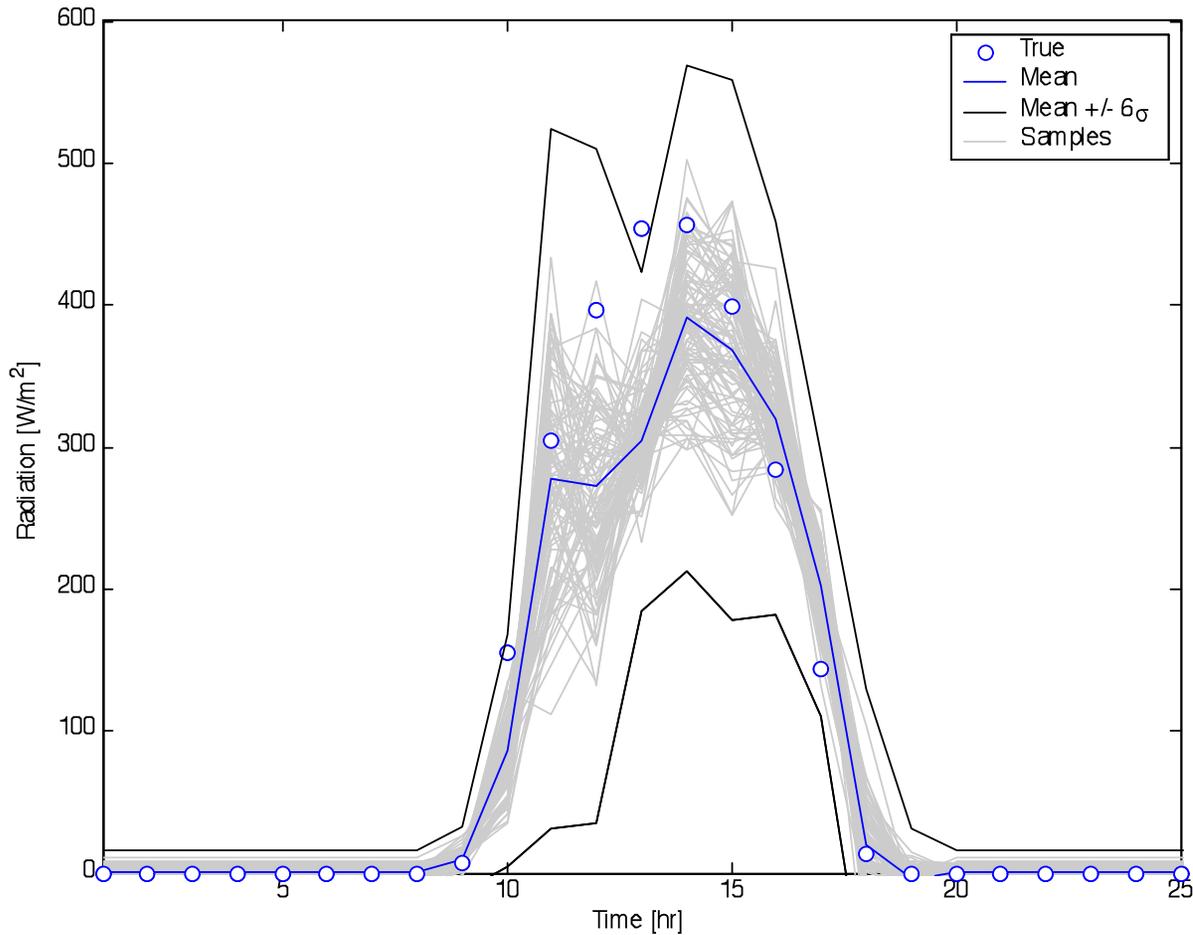
3. **Apply Maximum Likelihood:** $\log p(\mathbf{Y}|\eta) = -\frac{1}{2} \mathbf{Y} \mathbf{V}^{-1}(\mathbf{X}, \mathbf{X}, \eta) \mathbf{Y} - \frac{1}{2} \log \det(\mathbf{V}(\mathbf{X}, \mathbf{X}, \eta))$

4. **Posterior Distribution:** $\mathbf{Y}^P = \mathbf{V}(\mathbf{X}^P, \mathbf{X}, \eta^*) \mathbf{V}^{-1}(\mathbf{X}, \mathbf{X}, \eta^*) \mathbf{Y}$ **Forecast Mean**

$\mathbf{V}^P = \mathbf{V}(\mathbf{X}^P, \mathbf{X}^P, \eta^*) - \mathbf{V}(\mathbf{X}^P, \mathbf{X}, \eta^*) \mathbf{V}^{-1}(\mathbf{X}, \mathbf{X}, \eta^*) \mathbf{V}(\mathbf{X}, \mathbf{X}^P, \eta^*)$ **Covariance**

Uncertainty Quantification

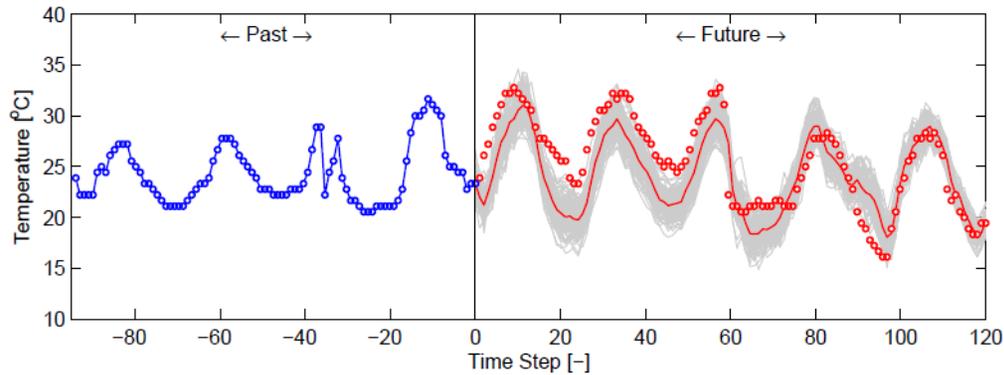
One-Day Ahead Forecast and Samples from Posterior Distribution



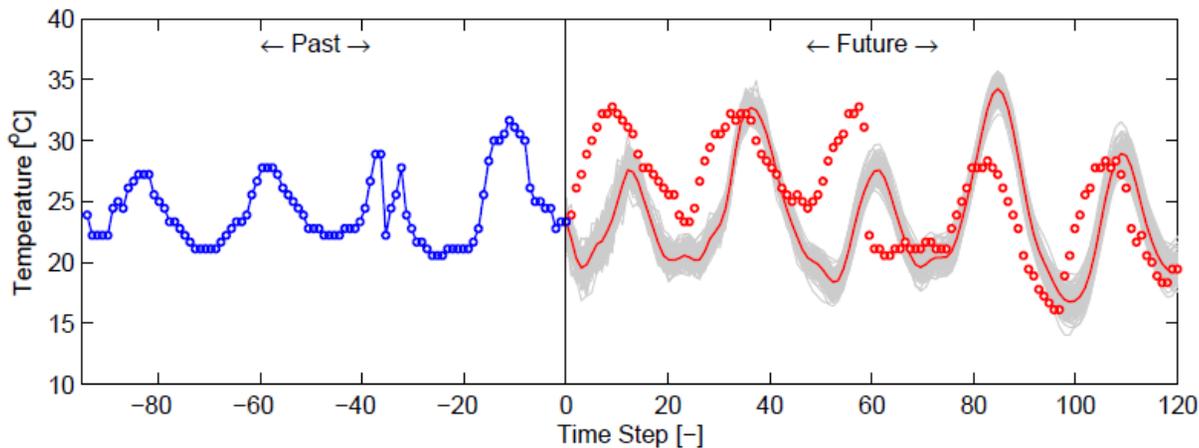
Covariance Structure *Sort of* Makes Physical Sense, Wide Uncertainty Bounds

Uncertainty Quantification

Ambient Temperature Forecast with GP Modeling *Zavala, A, et.al. 2009*



One Hour Ahead



5 Days Ahead

Time-Series Cannot Capture Physical Effects (Spatial), Inconsistent Uncertainty Bounds

GP Provides Accurate Interpolations but Poor Extrapolations (e.g. Geostatistics)

Uncertainty Quantification

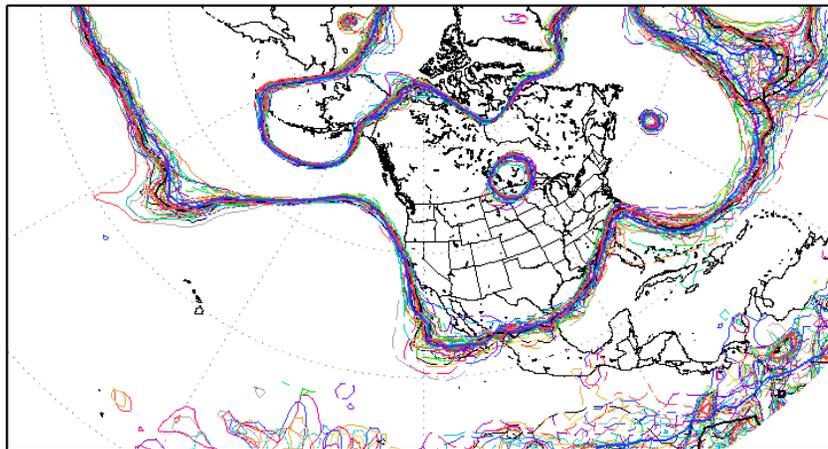
- **Advanced Meteorological Models (WRF)**
 - Detailed Physico-Chemical Phenomena
 - High Complexity 4-D Fields (10^6 States)



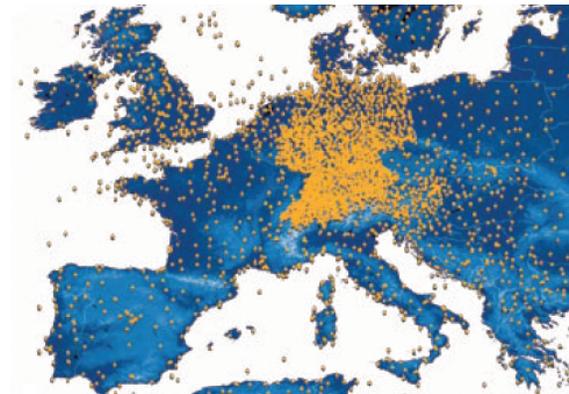
- **Model Reconciled to Measurements From Multiple Stations**

- **Reconciliation Techniques:**

- **3-D Var** *Courtier, et.al. 1998*
- **4-D Var (Moving Horizon Estimation)** *Navon et.al., 2007*
- **Extended and Ensemble Kalman Filter** *Eversen, et.al. 1998*

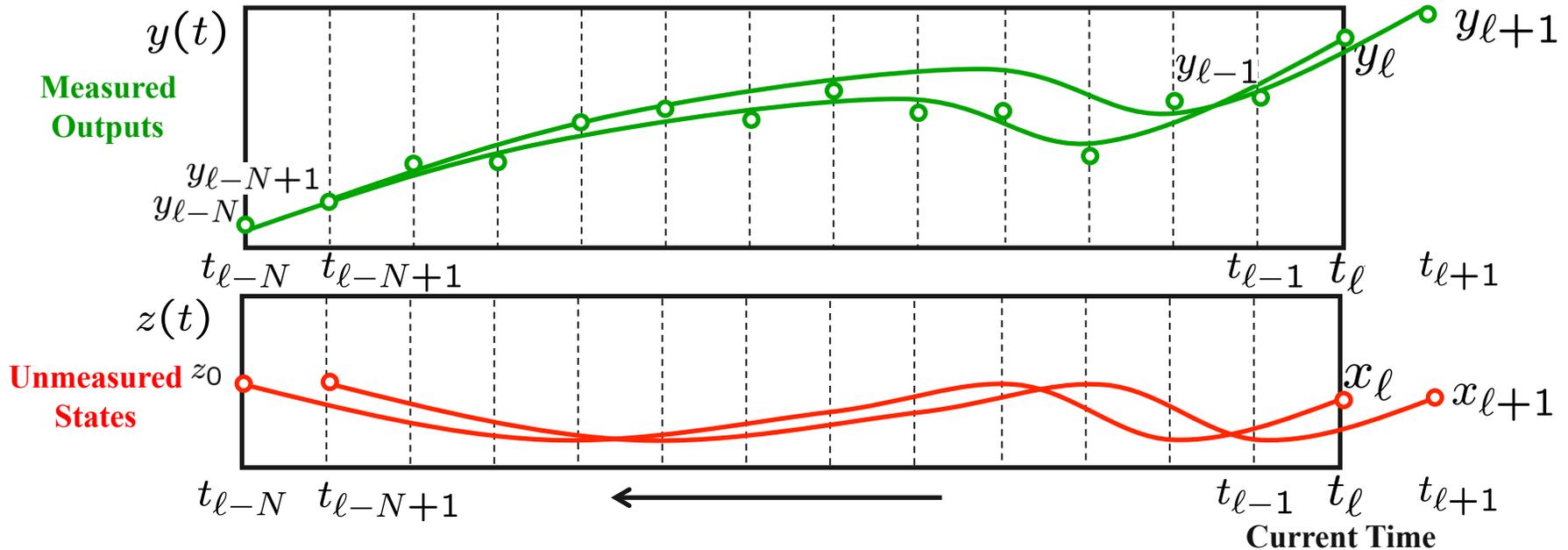


<http://www.emc.ncep.noaa.gov/gmb/ens/>



<http://www.meteoedia.com/>

4-D Var and Moving Horizon Estimation



$$\min_{p(t), z_0} \sum (y(t_k) - \underline{y_{l-k+N}})^T V_y^{-1} (y(t_k) - \underline{y_{l-k+N}})$$

$$\min_{p(t), z_0} \sum (y(t_k) - y_{l-k+N+1})^T V_y^{-1} (y(t_k) - y_{l-k+N+1})$$

WRF Model

$$\frac{dz}{dt} = \mathbf{f}(z(t), p(t), u(t))$$

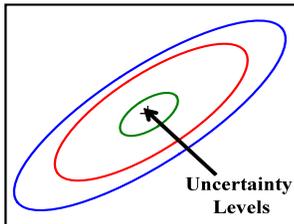
$$y(t) = \mathbf{g}(z(t), p(t), u(t))$$

$$z(0) = z_0 \text{ Uncertain}$$

$$\frac{dz}{dt} = \mathbf{f}(z(t), p(t), u(t))$$

$$y(t) = \mathbf{g}(z(t), p(t), u(t))$$

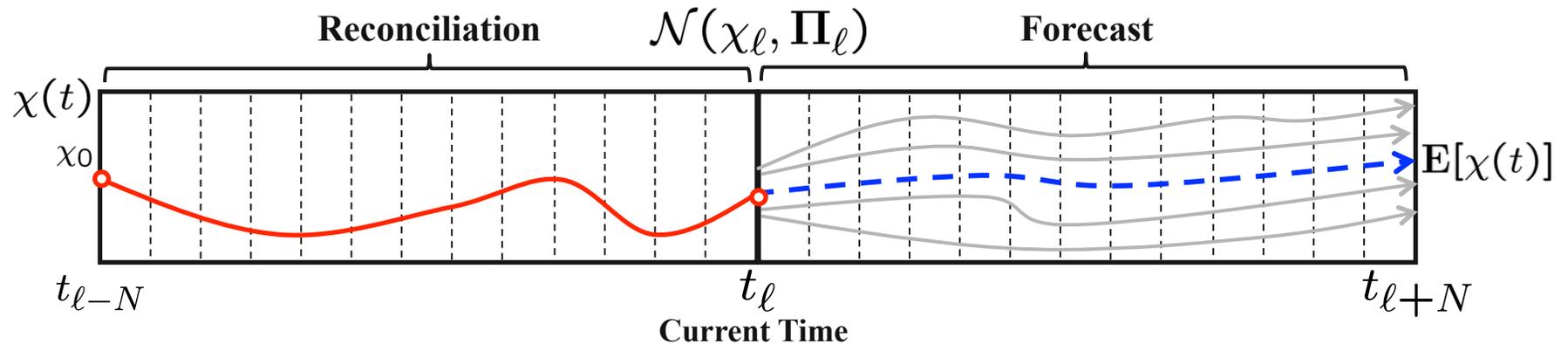
$$z(0) = z_0$$



$$\Pi_\ell \rightarrow 0$$

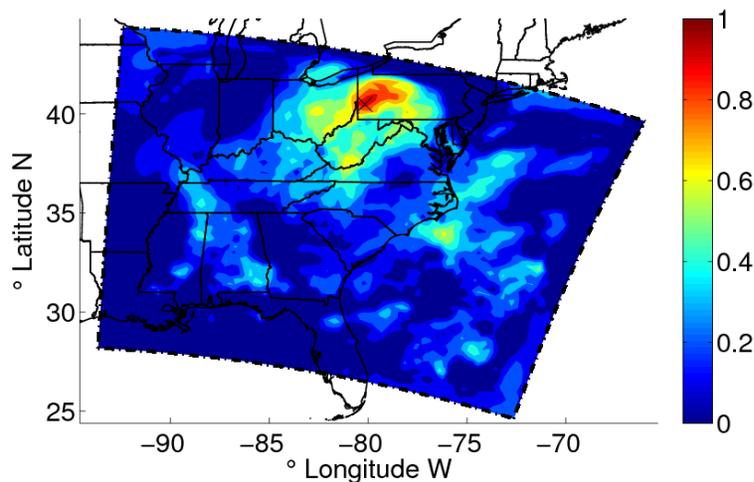
Uncertainty in Current State x_ℓ ?
Needed To Quantify Future Forecast

Ensemble Forecast Approach



Covariance Matrix is Huge ($10^6 \times 10^6$) But ...

- **Spatial Correlations Decay Exponentially** *Constantinescu, et.al., 2007*
- **Covariance Can be Approximated Using Gaussian Kernels** *Zavala, Constantinescu & A, 2009*



$$\Pi_{:,i,j} = \exp \left(-\frac{(x_j - x_i)^2 + (y_j - y_i)^2}{L_H^2} - \frac{(z_j - z_i)^2}{L_V^2} \right)$$

Ensemble Forecast Approach

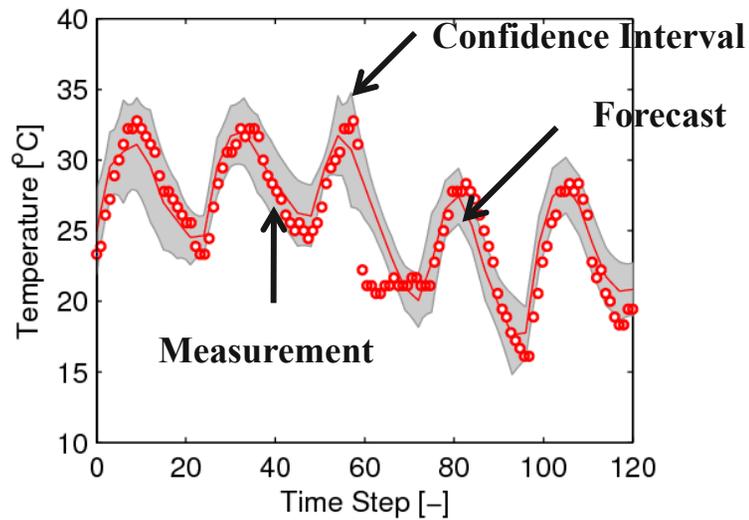
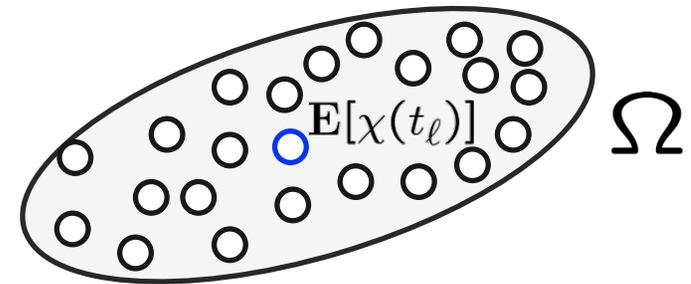
Ensemble Forecast Approach – Use WRF as Black-Box

Propagate Samples of Posterior Through Model

$$Y_{[i,j]} := \chi_i(t_{l+j}) = \underbrace{\mathcal{M}(\mathcal{M}(\dots\mathcal{M}(\chi_i(t_l))))}_{j \text{ times}}$$

$$E[Y] \approx \bar{Y} := \frac{1}{NS} \sum_{i=1}^{NS} Y_{[i,:]}$$

$$V \approx \frac{1}{NS - 1} \sum_{i=1}^{NS} (Y_{[i,:]} - \bar{Y})(Y_{[i,:]} - \bar{Y})^T$$



Hours (August 1st-5th)

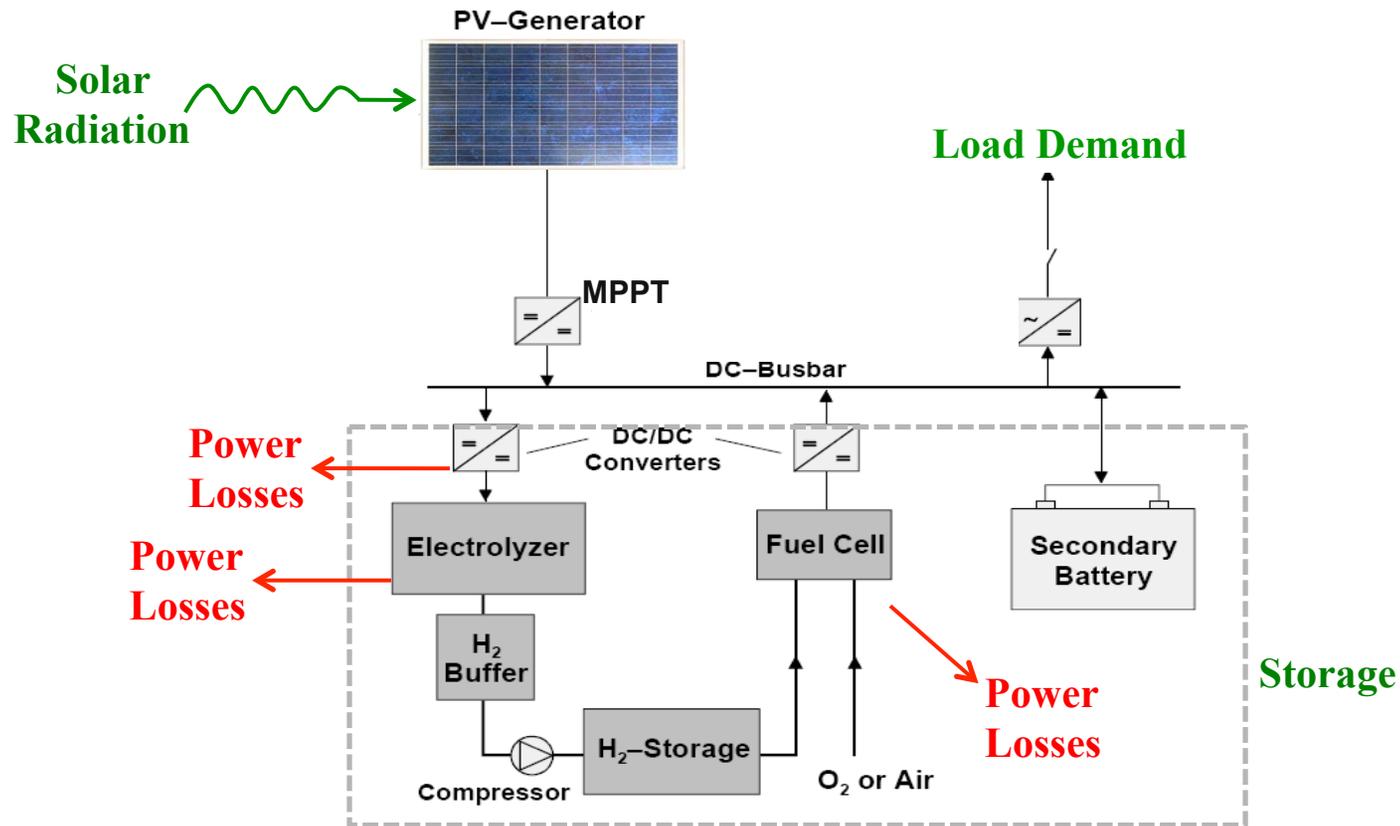
Validation Results, Pittsburgh Area 2006
5 Day Forecast and +/- 3s Intervals



Case Studies



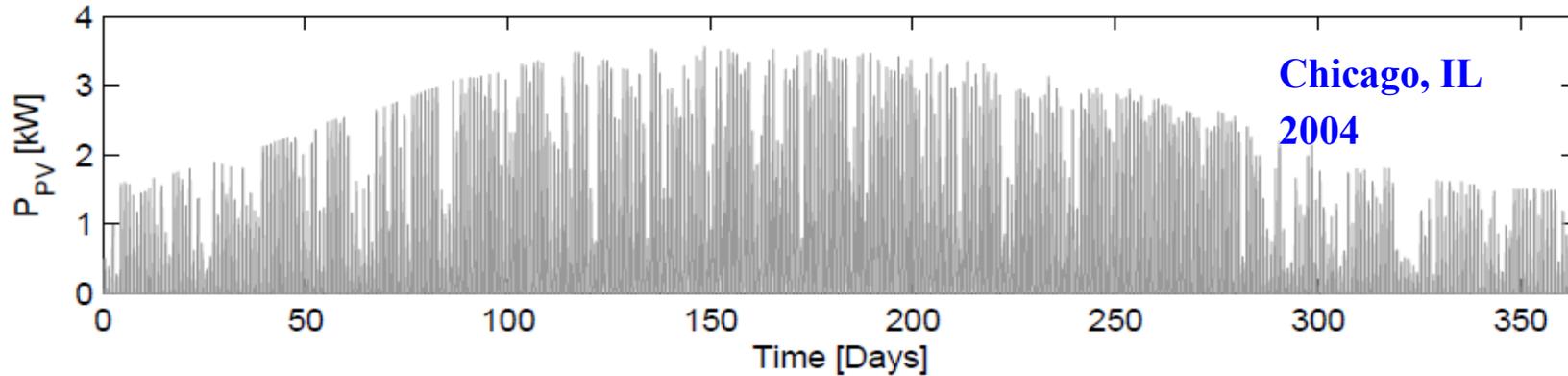
Hybrid Photovoltaic-H₂ System



- **Operating Costs Driven by Uncertain Radiation** *Ulleberg, 2004*
- **Performance Deteriorated by Multiple Power Losses**

Hybrid Photovoltaic-H₂ System

Effect of Forecast on Economics *Z., Anitescu, Krause 2009*



True Future Radiation

$$\min_{u(t)} \int_{t_\ell}^{t_\ell+N} \varphi(z(t), y(t), u(t), \chi(t)) dt$$

$$\frac{dz}{dt} = f(z(t), y(t), u(t), \chi(t))$$

$$0 = g(z(t), y(t), u(t), \chi(t))$$

$$0 \geq h(z(t), y(t), u(t), \chi(t))$$

$$z(0) = x_\ell$$

Minimize Operating Costs + Maximize H₂

**Production
Energy Balances**

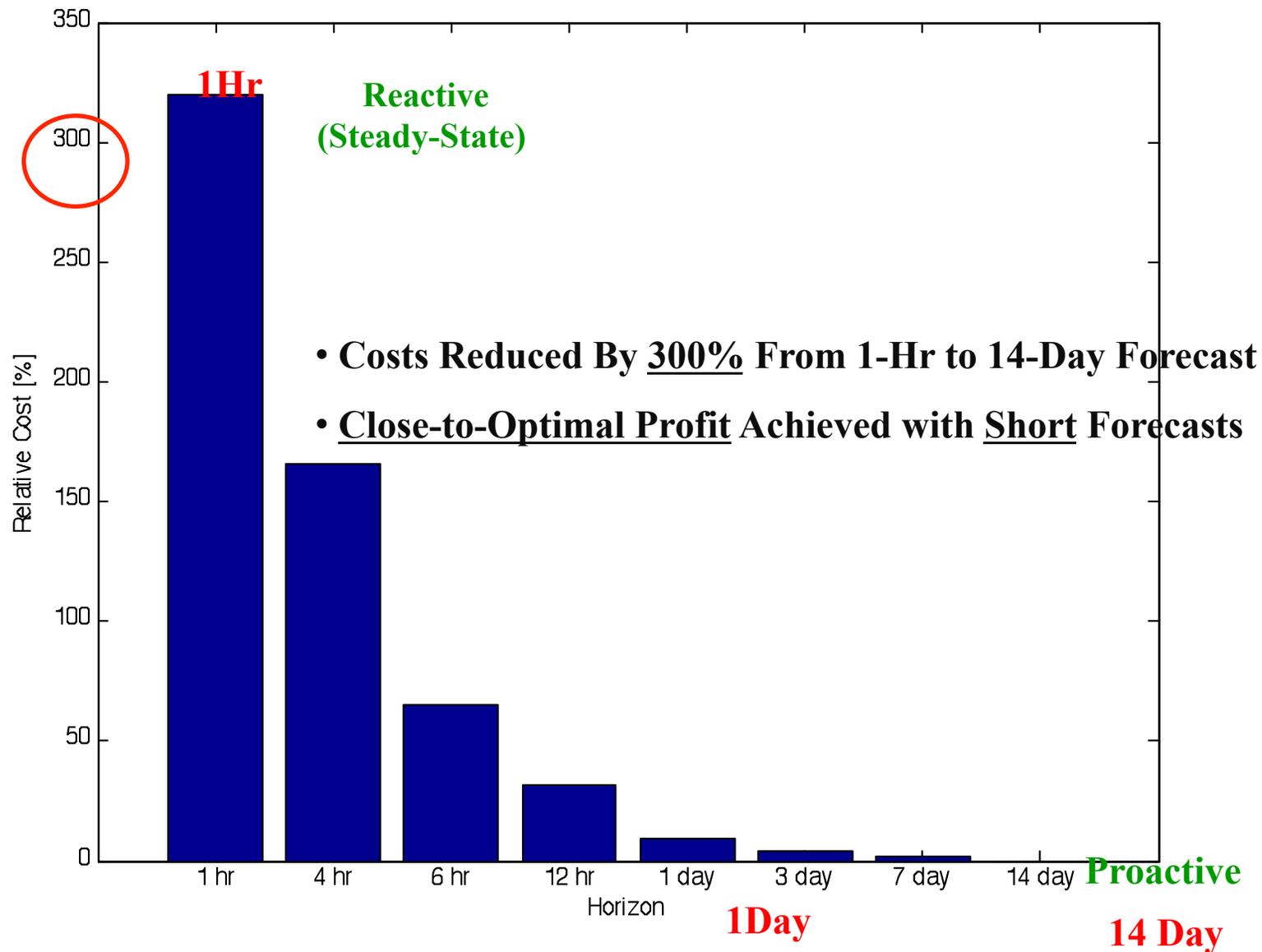
State-of-Charge, Fuel Cell and Electrolyzer

Limits

- **Forecast Horizon of One Year** – Highest Achievable Profit
- **Receding-Horizon with 1hr, 1 Day, ..., 14 Days Forecast** - 8,700 Problems in Each

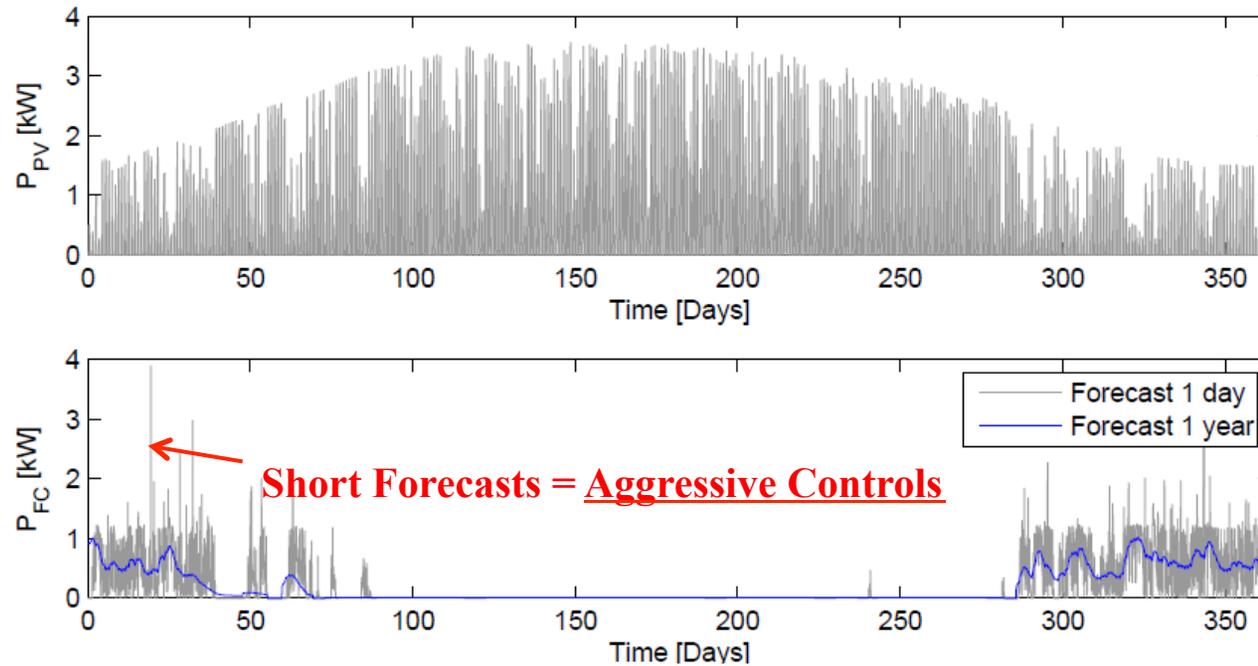
Scenario

Hybrid Photovoltaic-H₂ System



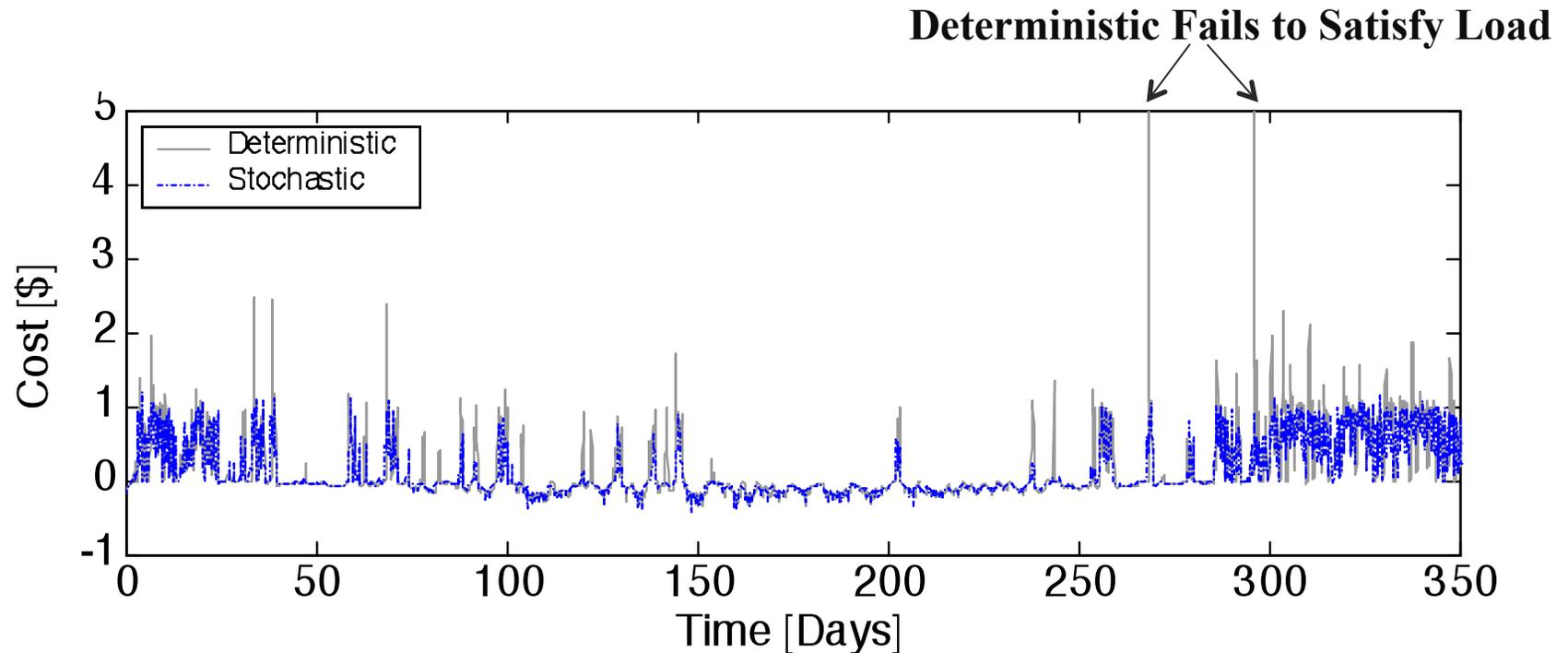
Hybrid Photovoltaic-H₂ System

Profiles of Fuel Cell Power



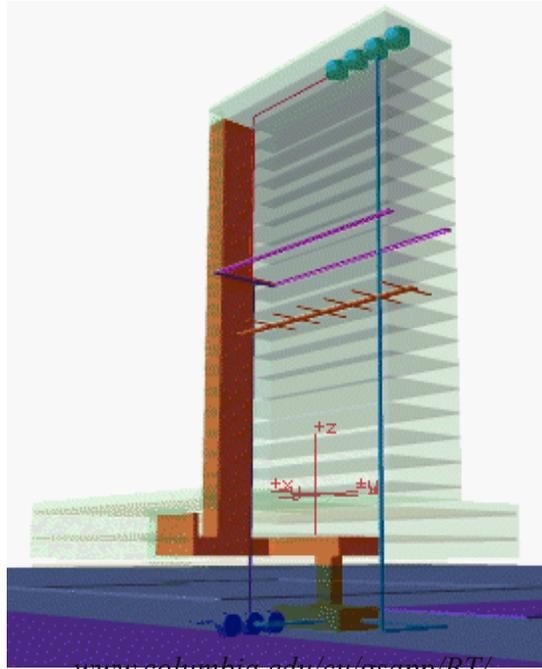
Hybrid Photovoltaic-H₂ System

Load Satisfaction Deterministic (“Optimization on Mean”) vs. Stochastic



Handling Stochastic Effects Particularly Critical in Grid-Independent Systems

Thermal Management of Building Systems



www.columbia.edu/cu/gsap/BT/LEVER/

Minimize Annual Heating and Cooling Costs

$$\min_{u(t)} \int_{t_\ell}^{t_\ell+N} [C_c(t)\varphi_c(t) + C_h(t)\varphi_h(t)] dt$$

$$C_I \cdot \frac{\partial T_I}{\partial \tau} = \varphi_h(\tau) - \varphi_c(\tau) - S \cdot \alpha' \cdot (T_I(\tau) - T_W(\tau, 0))$$

$$\frac{\partial T_W}{\partial \tau} = \beta \cdot \frac{\partial^2 T_W}{\partial x^2}$$

$$\alpha' (T_I(\tau) - T_W(\tau, 0)) = -k \cdot \left. \frac{\partial T_W}{\partial x} \right|_{(\tau, 0)}$$

$$\alpha'' (T_W(\tau, L) - T_A(\tau)) = -k \cdot \left. \frac{\partial T_W}{\partial x} \right|_{(\tau, L)}$$

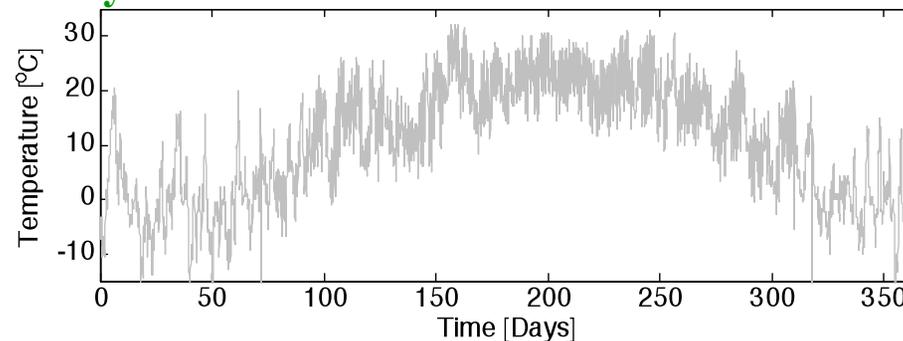
$$T_I(0) = T_I^\ell$$

$$T_W(0, x) = T_W^\ell(x)$$

Energy Balances

NLP with 100,000 Constraints & 20,000 Degrees of Freedom

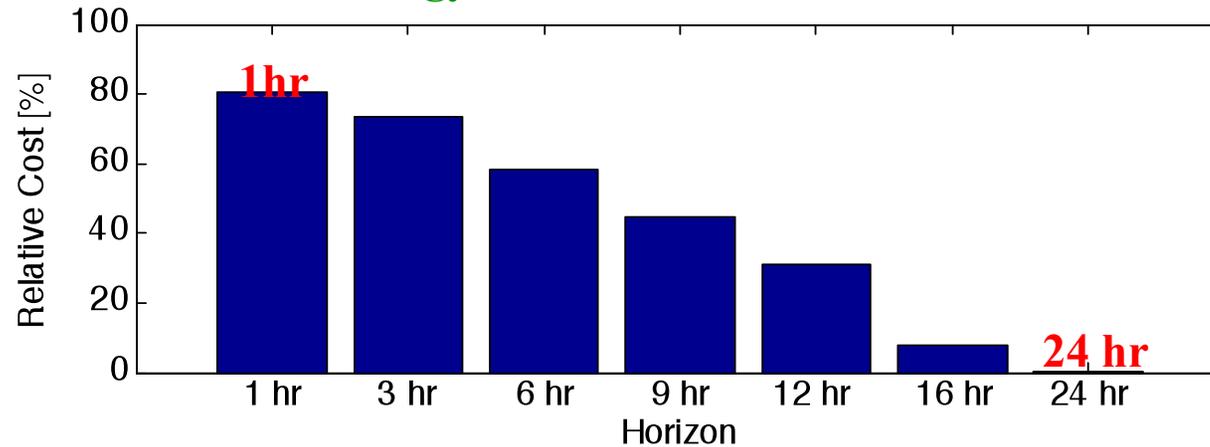
Time-Varying Electricity Price → Peak & Off-Peak



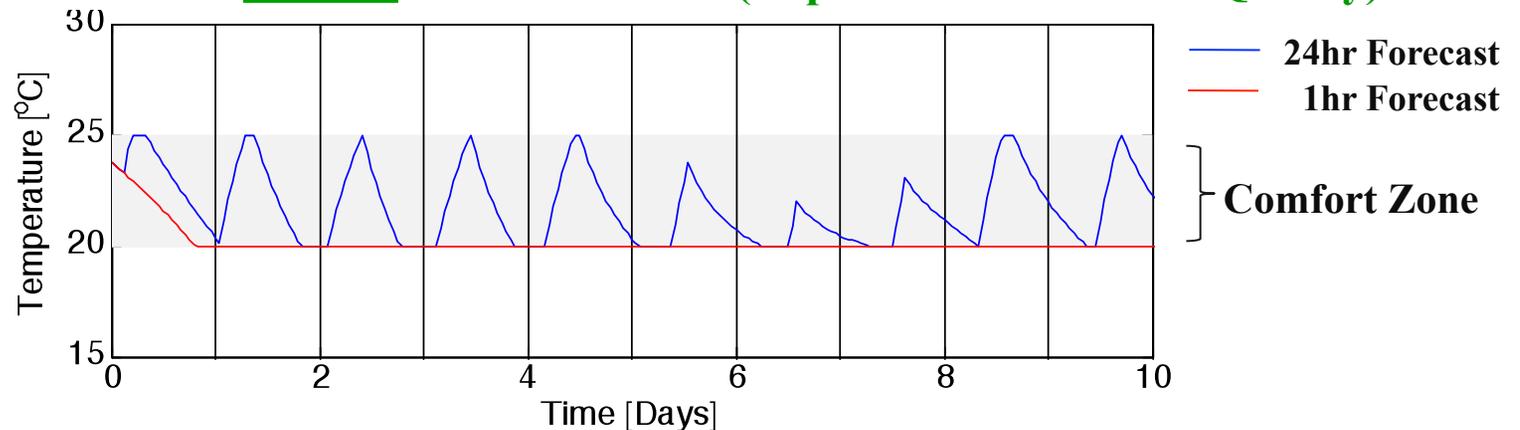
Pittsburgh, PA 2006

Thermal Management of Building Systems

Effect of Forecast on Energy Costs



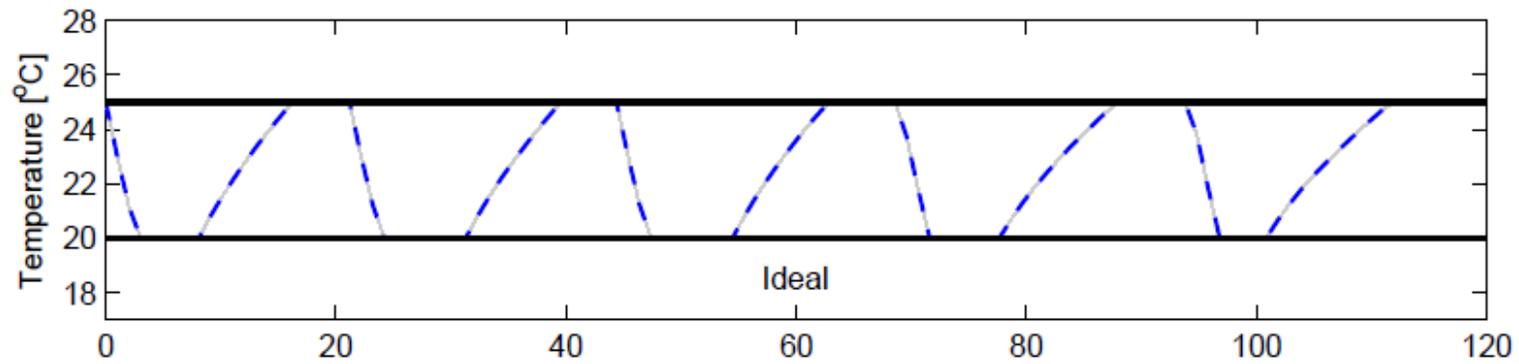
Forecast Leads to 20-80% Cost Reduction (Depends on Insulation Quality)



Exploit Comfort Zone and Weather Info to Heat/Cool when Cheaper *Braun, 1990*

Thermal Management of Building Systems

Performance Optimizer using WRF and GP Model Forecasts



**Perfect
Forecast**



Conclusions and Future Work

Conclusions and Future Work

Integrative Study of Weather Forecast-Based Optimization

WRF Model + Ensemble Approach + Stochastic Receding-Horizon

Important Economic Benefits, Niche Market is Huge

New Algorithms and Formulations Needed

- **We showed that stochastic formulation matters (deterministic results in big losses).**
- **We showed that weather forecast inclusions results in 20-80% cost reduction**
- **Weather uncertainty is a hard, important, problem that data-only methods (such as GP) are unlikely to crack**

Future and On-Going Work

Convergence of SAA Approximations for Stochastic Receding-Horizon

Variance Reduction Control Formulations

Integration Gaussian Process + WRF Forecasts

Conclusions and Future Work

Integrative Study of Weather Forecast-Based Optimization

WRF Model + Ensemble Approach + Stochastic Receding-Horizon

Important Economic Benefits, Niche Market is Huge

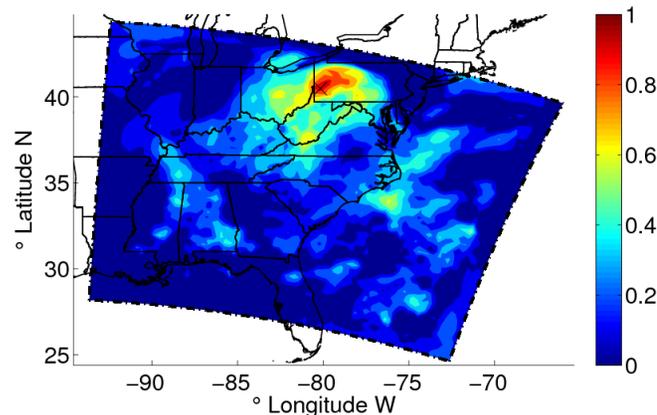
New Algorithms and Formulations Needed

Future and On-Going Work

Convergence of SAA Approximations for Stochastic Receding-Horizon

Variance Reduction Control Formulations

Integration Gaussian Process + WRF Forecasts



WRF Model Provides Coarse Forecasts

(Km, Hour Scales)

Gaussian Process Model to Create

High-Fidelity Forecasts

(Meters, Minutes)

Collaborators

Dr. Victor Zavala, Mathematics-Argonne

Dr. Emil Constantinescu, Mathematics-Argonne

Dr. Ted Krause, Chemical Technology-Argonne

Weather Forecast-Based Optimization of Industrial Systems

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March 30th, 2009

Weather Forecast-Based Optimization of Integrated Energy Systems

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