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# Large-Scale Nonlinear Parameter Estimation with IPOPT

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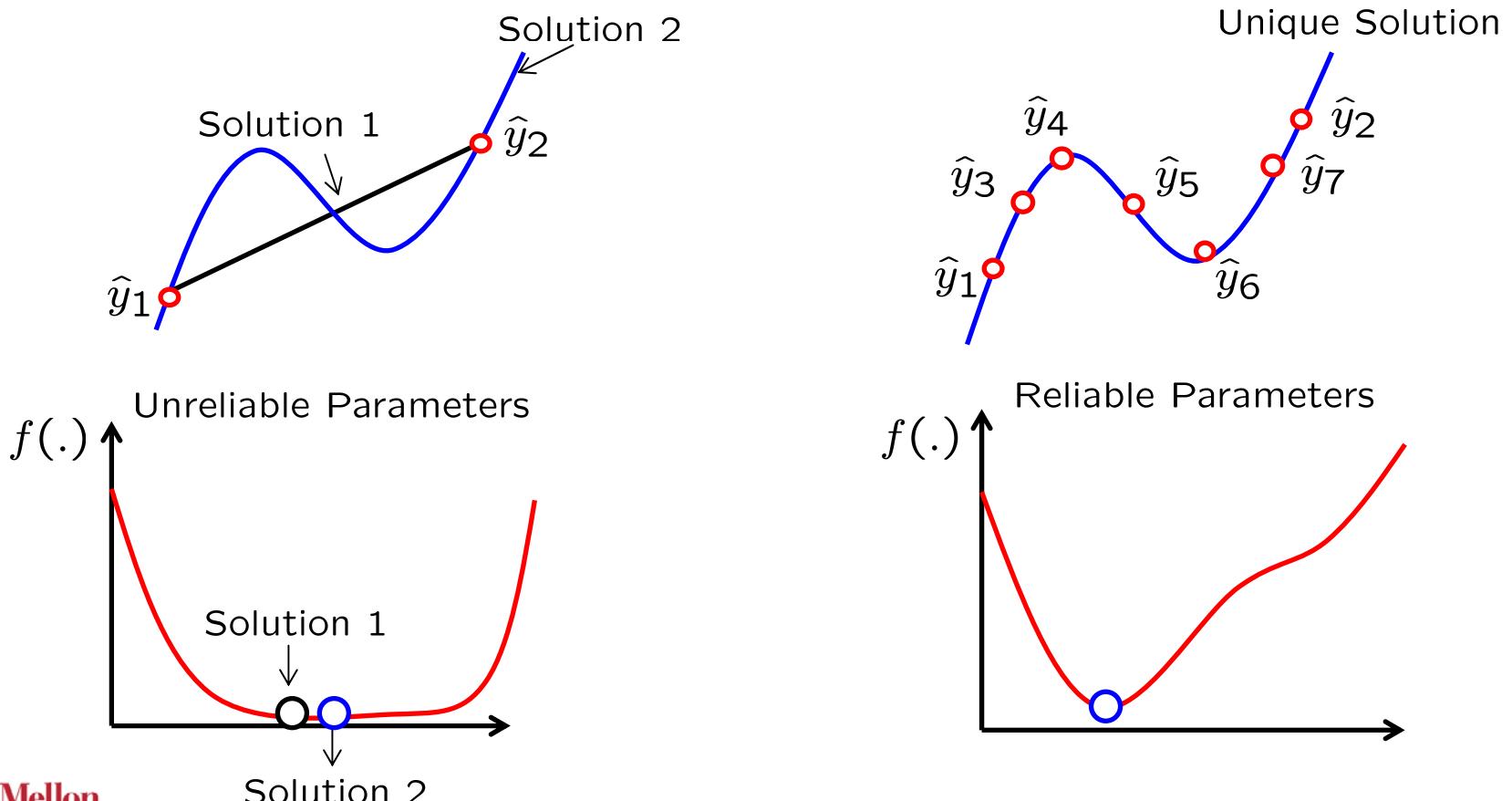


# Background

# Parameter Estimation

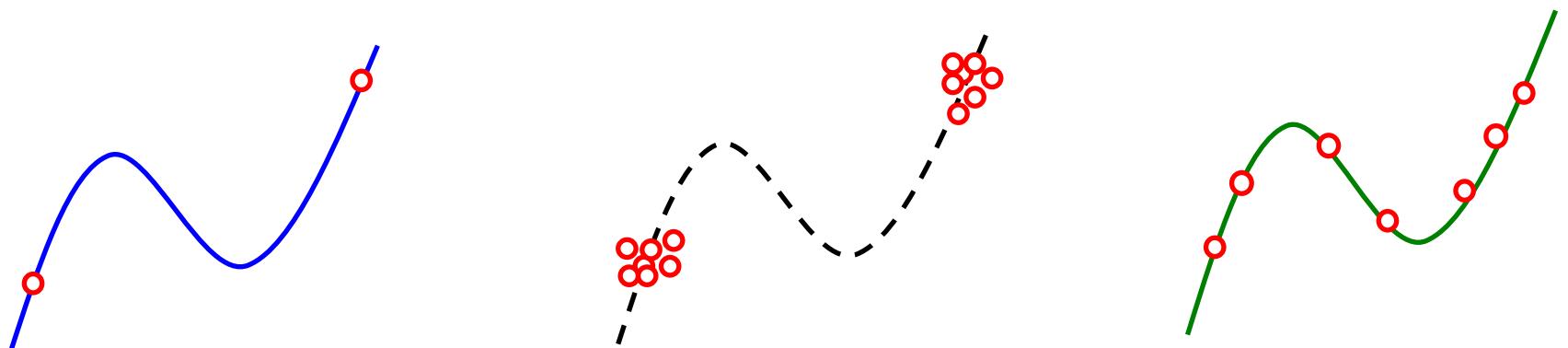
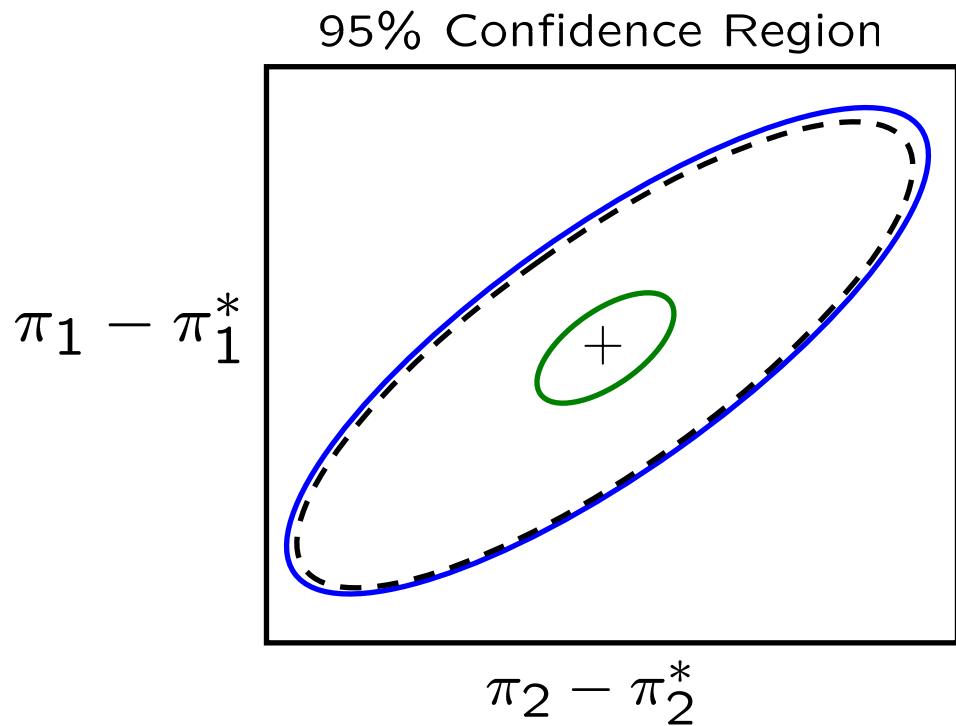
$$\min f(.) = \sum_{k=1}^{NS} (y_k - \hat{y}_k^M)^2$$

$$y_k = \pi_1 + \pi_2 x_k + \pi_3 x_k^2 + \pi_4 x_k^3$$
$$k = 1, \dots, NS$$



# Parameter Estimation

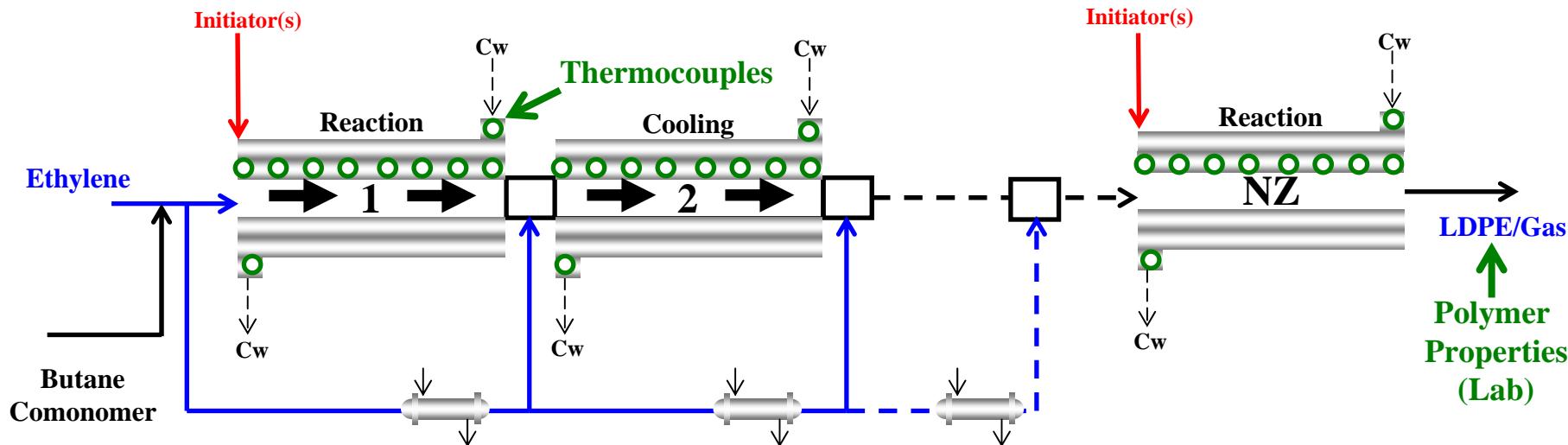
## Confidence Regions





# Rigorous Models in Process Engineering

# High-Pressure LDPE Tubular Reactors



	On-line Parameters	Kinetic Parameters
<b>Material &amp; Energy</b>	$\left\{ F_j \left[ \frac{dy_j(z)}{dz}, y_j(z), w_j(z), z, \pi_j, \Pi \right] = 0 \right.$	$\uparrow$
<b>Physical Properties</b>	$G_j \left[ y_j(z), w_j(z), z, \pi_j, \Pi \right] = 0$	$\uparrow$
<b>Zone Transitions</b>	$y_j(0) = \phi(y_{j-1}(z_{L_{j-1}}), F_{f_j})$	

500 ODEs

1000 AEs

\* Stiffness + Highly Nonlinear + Parametric Sensitivity + Algebraic Coupling

# High-Pressure LDPE Tubular Reactors

## Complex Kinetic Mechanisms

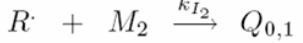
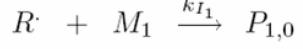
~ 35 Elementary Reactions  
~100 Kinetic Parameters

$$k_i = k_i^0 \exp \left[ -\frac{\Delta E_{a_i} + P \Delta E_{v_i}}{RT} \right]$$

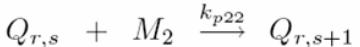
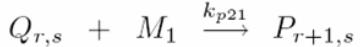
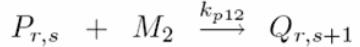
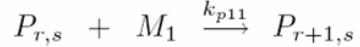
### Initiator decomposition



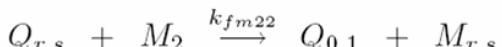
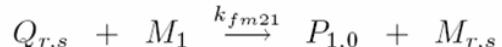
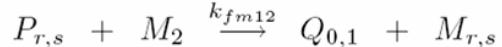
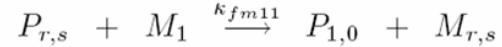
### Chain Initiation



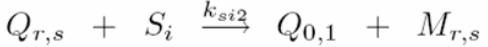
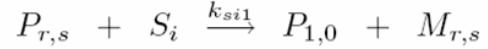
### Chain Propagation



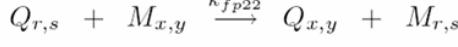
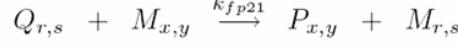
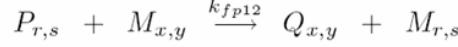
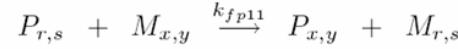
### Chain Transfer to Monomer



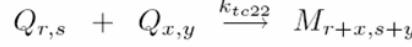
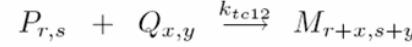
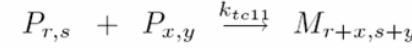
### Chain Transfer to Solvent



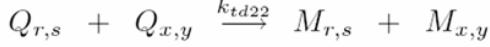
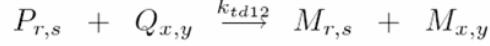
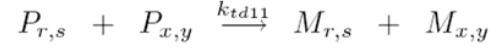
### Chain Transfer to Polymer



### Termination by Combination



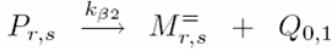
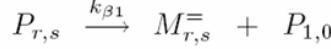
### Termination by Disproportionation



### Backbitting



### $\beta$ -scission





# Large-Scale Parameter Estimation

# Parameter Estimation Problem

## - Maximum Likelihood Estimation

$$\min_{\Pi, \pi_{k,j}} \left\{ \sum_{k=1}^{NS} \sum_{j=1}^{NZ} \sum_{i=1}^{NM(j)} \left( y_{k,j}(z_i) - y_{k,j,i}^M \right)^T \mathbf{V}_y^{-1} \left( y_{k,j}(z_i) - y_{k,j,i}^M \right) + \sum_{k=1}^{NS} \left( w_{k,NZ} - w_{k,NZ}^M \right)^T \mathbf{V}_w^{-1} \left( w_{k,NZ} - w_{k,NZ}^M \right) \right\}$$

s.t.

$$\left. \begin{array}{l} \mathbf{F}_{k,j} \left[ \frac{dy_{k,j}(z)}{dz}, y_{k,j}(z), w_{k,j}(z), z, \pi_{k,j}, \Pi \right] = 0 \\ \mathbf{G}_{k,j} \left[ y_{k,j}(z), w_{k,j}(z), z, \pi_{k,j}, \Pi \right] = 0 \\ y_{k,j}(0) = \phi(y_{k,j-1}(z_{L_{k,j-1}}), F_{f_{k,j}}) \\ j \in \{1..NZ\}, \quad k \in \{1..NS\} \end{array} \right\}$$

Standard  
Least-Squares

Rigorous  
DAE Model

<b>1 data set</b> 500 ODEs 1000 AEs	<b>5 data sets</b> 2500 ODEs 5000 AEs
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## - Previously Intractable Problems

- Full Discretization Approach → Large-Scale NLPs

# Solution of Large-Scale NLP

- Robust General Algorithms -IPOPT- vs. Ad-Hoc Estimation Algorithms

$$\begin{array}{ll} \min & f(x) \\ \text{s.t.} & c(x) = 0 \\ & x \geq 0 \end{array} \quad \xrightarrow{\hspace{1cm}} \quad \begin{array}{ll} \min & \varphi_{\mu_\ell}(x) = f(x) - \mu_\ell \sum_{i=1}^{nx} \ln(x^{(i)}) \\ \text{s.t.} & c(x) = 0 \end{array}$$

NLP BP

Main Idea: Solve Sequence of BPs with  $\mu_\ell \rightarrow 0$

$$\begin{array}{ll} \nabla_x f(x) + \nabla_x c(x) \lambda - \nu &= 0 \\ c(x) &= 0 \\ XVe - \mu_\ell e &= 0 \end{array} \quad \xrightarrow{\hspace{1cm}} \quad \begin{array}{l} \text{Newton's Method} \\ \text{Exact Derivatives} \end{array} \quad \left[ \begin{array}{ccc} H_k & A_k & -I \\ A_k^T & 0 & 0 \\ V_k & 0 & X_k \end{array} \right] \left[ \begin{array}{c} \Delta x \\ \Delta \lambda \\ \Delta \nu \end{array} \right] = - \left[ \begin{array}{c} \nabla f(x_k) + A_k \lambda_k - \nu_k \\ c(x_k) \\ X_k V_k e - \mu_\ell e \end{array} \right]$$

- Non-Convex, Ill-Posed – Negative Curvature- Filter Line-Search
  - Jacobian Rank-Deficient

Inertia Correction

$$\left[ \begin{array}{ccc} H_k + \delta_1 I & A_k & -I \\ A_k^T & -\delta_2 I & 0 \\ V_k & 0 & X_k \end{array} \right] \left[ \begin{array}{c} \Delta x \\ \Delta \lambda \\ \Delta \nu \end{array} \right] = - \left[ \begin{array}{c} \nabla f(x_k) + A_k \lambda_k - \nu_k \\ c(x_k) \\ X_k V_k e - \mu_\ell e \end{array} \right]$$

- IF  $\delta_1, \delta_2 = 0$  at Solution – Parameters Uniquely Determined

# Results – Standard Least-Squares

- Single Data Set (On-line Parameters)

Grade	Constraints	Parameters	LB	UB	Iterations	CPUs	Sparsity Structure	
							NZJ	NZH
A	11955	32	374	361	11	17.03	166425	87954
B	11283	32	374	361	8	10.06	138666	76890

Fill-In

↑

On-Line Estimation

- Multiple Data Sets (On-line Parameters + Kinetics)

Data Sets	Constraints	DOF	LB	UB	Iterations	CPUs	NZJ	NZH
3	33900	121	1246	1207	68	451.51	520275	552738
6	68421	217	2467	2389	58	900.21	1058412	1119258



Bottleneck -Memory Requirements-  
Factorization KKT Matrix

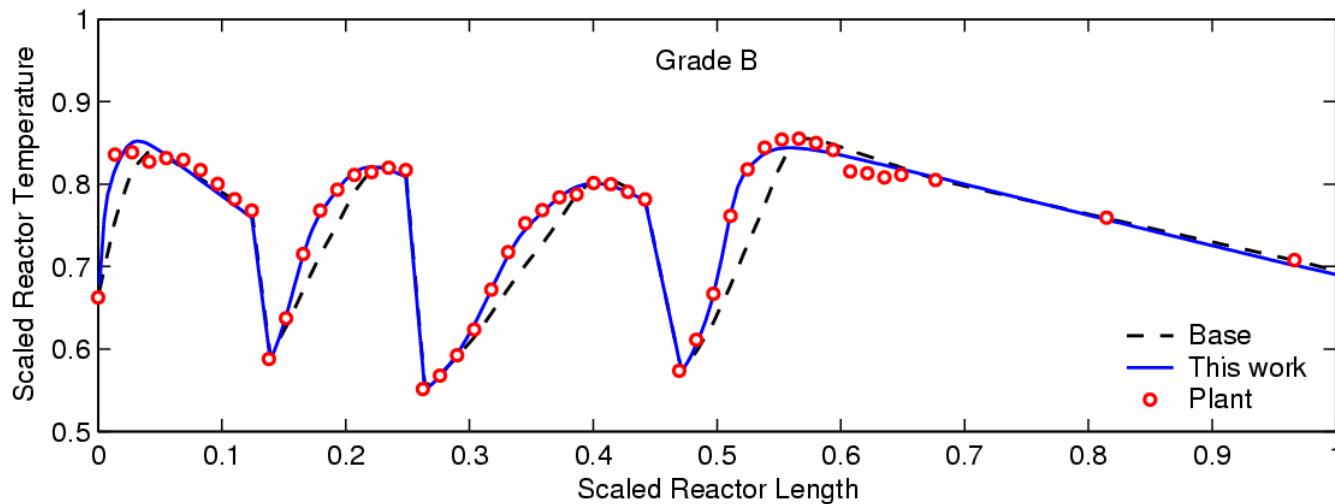
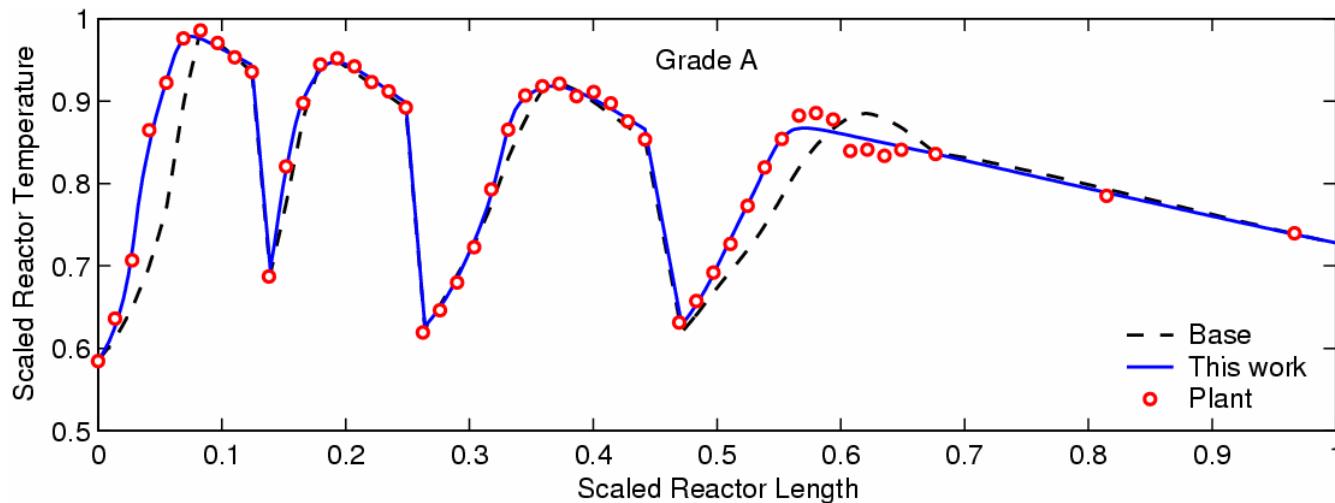
$$\begin{bmatrix} H_k + \delta_1 I & A_k & -I \\ A_k^T & -\delta_2 I & 0 \\ V_k & 0 & X_k \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta \lambda \\ \Delta \nu \end{bmatrix} = - \begin{bmatrix} \nabla f(x_k) + A_k \lambda_k - \nu_k \\ c(x_k) \\ X_k V_k e - \mu_\ell e \end{bmatrix}$$

Tailored Linear Algebra

$$\begin{bmatrix} K_1 & & Q_1 \\ & K_2 & Q_2 \\ & & \ddots \\ Q_1^T & Q_2^T & \dots & D_{\Pi} \end{bmatrix} \begin{bmatrix} \Delta s_1 \\ \Delta s_2 \\ \vdots \\ \Delta \Pi \end{bmatrix} = - \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_{\Pi} \end{bmatrix}$$

# Results – Standard Least-Squares

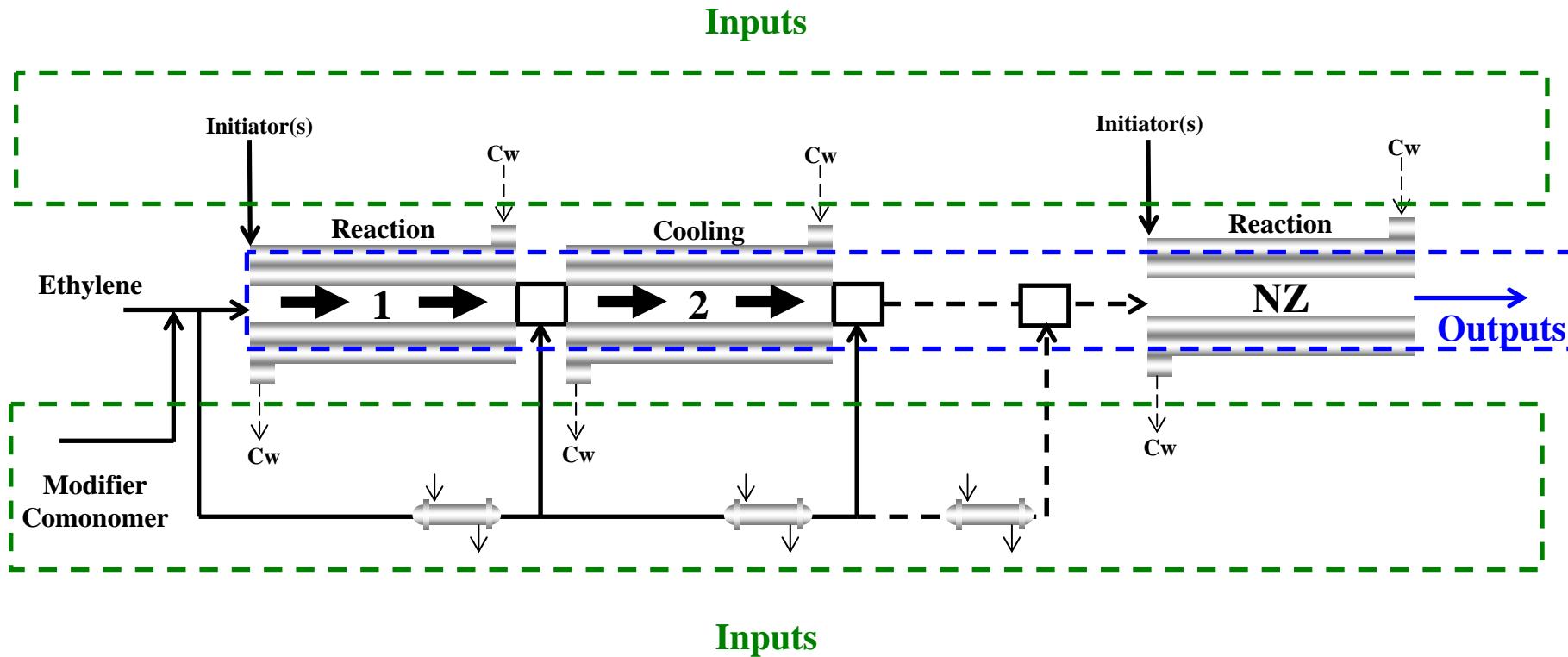
Improved Match of Reactor Temperature Profile → On-line Estimation



# Advanced Regression Methods

## Errors-In-Variables (EVM)

- Standard Least Squares
- Errors in Output Variables - *Biased* Parameters
- EVM - Errors in Output AND Input Variables - *Unbiased* Parameters



# Advanced Regression Methods

## Errors-In-Variables (EVM)

**EVM Drawback - Degrees of Freedom**

$$DOF = \Pi + \sum_{k=1}^{NS} \sum_{j=1}^{NZ} \pi_{k,j} + \sum_{k=1}^{NS} \sum_{j=1}^{NZ} \sum_{i=1}^{NM_u(j)} u_{k,j,i}$$

Formulation is Straightforward

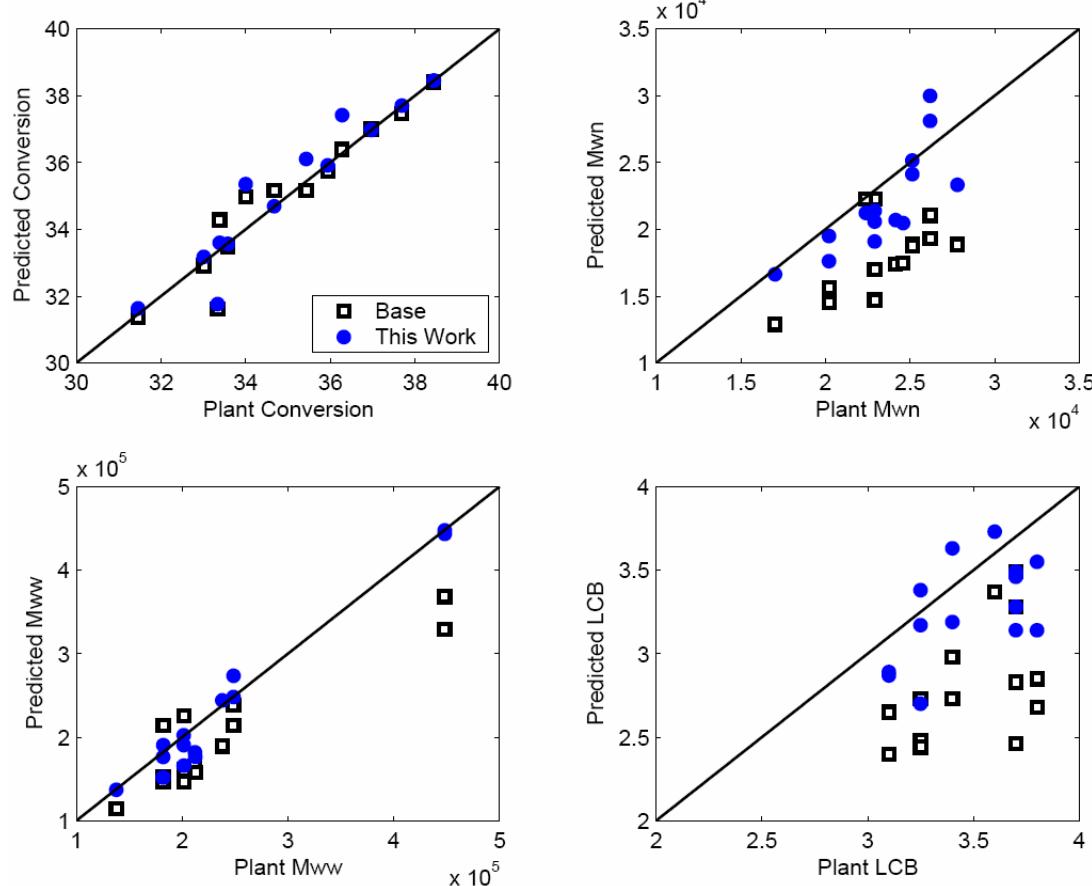
$$\begin{aligned} \min_{\Pi, \pi_{k,j}, u_{k,j}} \quad & \sum_{k=1}^{NS} \sum_{j=1}^{NZ} \sum_{i=1}^{NM(j)} \left( y_{k,j}(z_i) - y_{k,j,i}^M \right)^T \mathbf{V}_y^{-1} \left( y_{k,j}(z_i) - y_{k,j,i}^M \right) \\ & + \sum_{k=1}^{NS} \left( w_{k,NZ} - w_{k,NZ}^M \right)^T \mathbf{V}_w^{-1} \left( w_{k,NZ} - w_{k,NZ}^M \right) \\ & + \sum_{k=1}^{NS} \sum_{j=1}^{NZ} \left( u_{k,j} - u_{k,j}^M \right)^T \mathbf{V}_u^{-1} \left( u_{k,j} - u_{k,j}^M \right) \end{aligned}$$

## EVM vs. Standard Least Squares

Data Sets	Constraints	DOF	LB	UB	Iterations	CPUs	NZJ	NZH
6 (EVM)	68627	529	2653	2575	71	1010.74	1059512	1119780
6 (SLS)	68421	217	2467	2389	58	900.21	1058412	1119258

# Results – Advanced Regression Methods

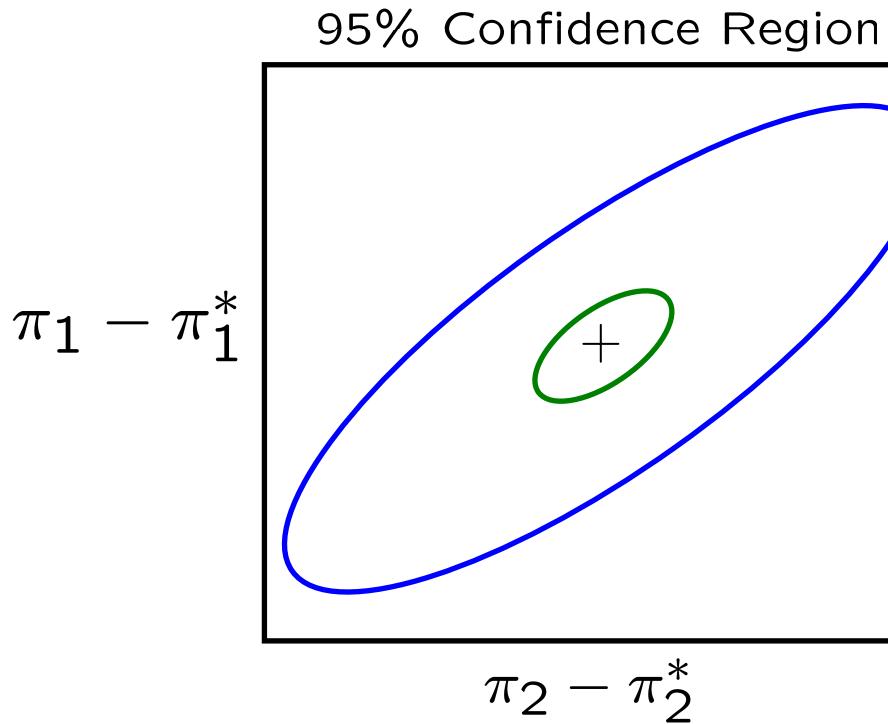
## Improved Prediction of Polymer Molecular Properties



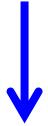
Average Deviation - 14 Different Data Sets

	Conversion(%)	M <sub>wn</sub> (%)	M <sub>ww</sub> (%)	LCB(%)	Density(%)
Industrial Model	1.49	23.24	18.58	19.20	0.0965
This Work	0.12	6.20	3.31	6.27	0.0875

# Post-Optimal Analysis



$$(\boldsymbol{\pi} - \boldsymbol{\pi}^*)^T V_{\boldsymbol{\pi}}^{-1} (\boldsymbol{\pi} - \boldsymbol{\pi}^*) \leq \chi^2(\alpha, n_{\boldsymbol{\pi}})$$



Sensitivity Information

$$V_{\boldsymbol{\pi}}^{-1} \approx \frac{\partial \boldsymbol{\pi}}{\partial y^M}^T V_y^{-1} \frac{\partial \boldsymbol{\pi}}{\partial y^M}$$

# Post-Optimal Analysis - NLP Sensitivity

$$\begin{array}{ll} \min & f(x, p) \\ \text{s.t.} & c(x, p) = 0 \\ & x \geq 0 \end{array} \quad \left. \right\} P(p)$$

## Solution Triplet

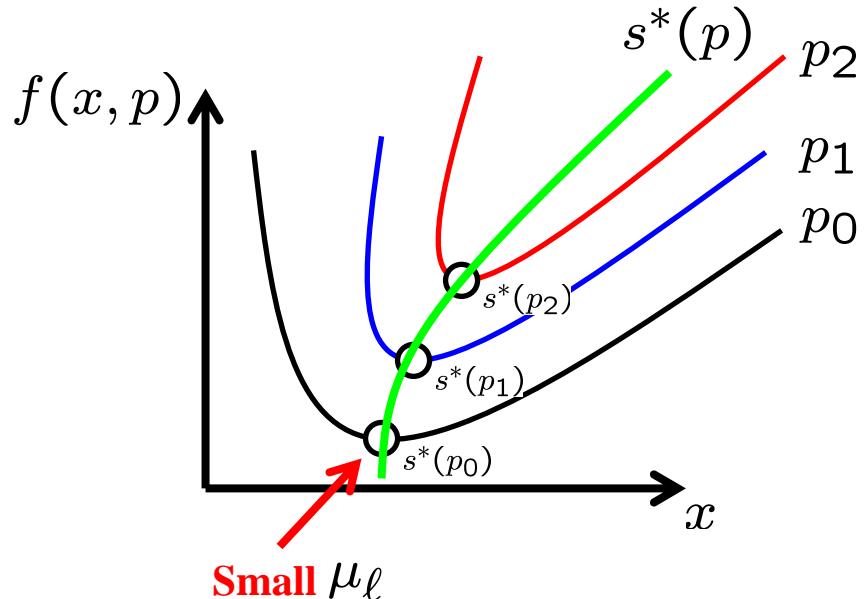
$$s^*(p)^T = [x^{*T} \ \lambda^{*T} \ \nu^{*T}]$$

$$\downarrow \quad \quad \quad \downarrow$$

$$\hat{y}^M \quad \pi_j, \Pi$$

## Optimality Conditions of $P(p)$

$$\begin{aligned} \nabla_x f(x, p) + \nabla_x c(x, p) \lambda - \nu &= 0 \\ c(x, p) &= 0 \\ XVe &= 0 \end{aligned}$$



NLP Sensitivity - Existence and Differentiability of Path  $s^*(p)$  - Fiacco, 1982

-  $\frac{\partial s}{\partial p} \Big|_{p_0}$  **Exists and is Unique**

# Post-Optimal Analysis - NLP Sensitivity

Obtaining  $\frac{\partial s}{\partial p} \Big|_{p_0}$

Optimality Conditions of  $P(p)$

$$\begin{aligned} \nabla_x \mathcal{L} = \nabla_x f(x, p) + \nabla_x c(x, p) \lambda - \nu &= 0 \\ c(x, p) &= 0 \\ XVe &= 0 \end{aligned} \quad \left. \right\} \quad \mathbf{F}(s, p) = 0$$

Apply Implicit Function Theorem to  $\mathbf{F}(s, p) = 0$  around  $(p_0, s^*(p_0))$

$$\frac{\partial \mathbf{F}(s^*(p_0), p_0)}{\partial s} \frac{\partial s}{\partial p} \Big|_{p_0} + \frac{\partial \mathbf{F}(s^*(p_0), p_0)}{\partial p} = 0$$

$$\left[ \begin{array}{ccc} W(s^*(p_0)) & A(x^*(p_0)) & -I \\ A(x^*(p_0))^T & 0 & 0 \\ V^*(p_0) & 0 & X^*(p_0) \end{array} \right] \left[ \begin{array}{c} \frac{\partial x}{\partial p} \\ \frac{\partial \lambda}{\partial p} \\ \frac{\partial \nu}{\partial p} \end{array} \right] + \left[ \begin{array}{c} \nabla_{x,p} \mathcal{L}(s^*(p_0)) \\ \nabla_p c(x^*(p_0)) \\ 0 \end{array} \right] = 0$$

KKT Matrix IPOPT

$$\left[ \begin{array}{ccc} W(x_k, \lambda_k) & A(x_k) & -I \\ A(x_k)^T & 0 & 0 \\ V_k & 0 & X_k \end{array} \right]$$

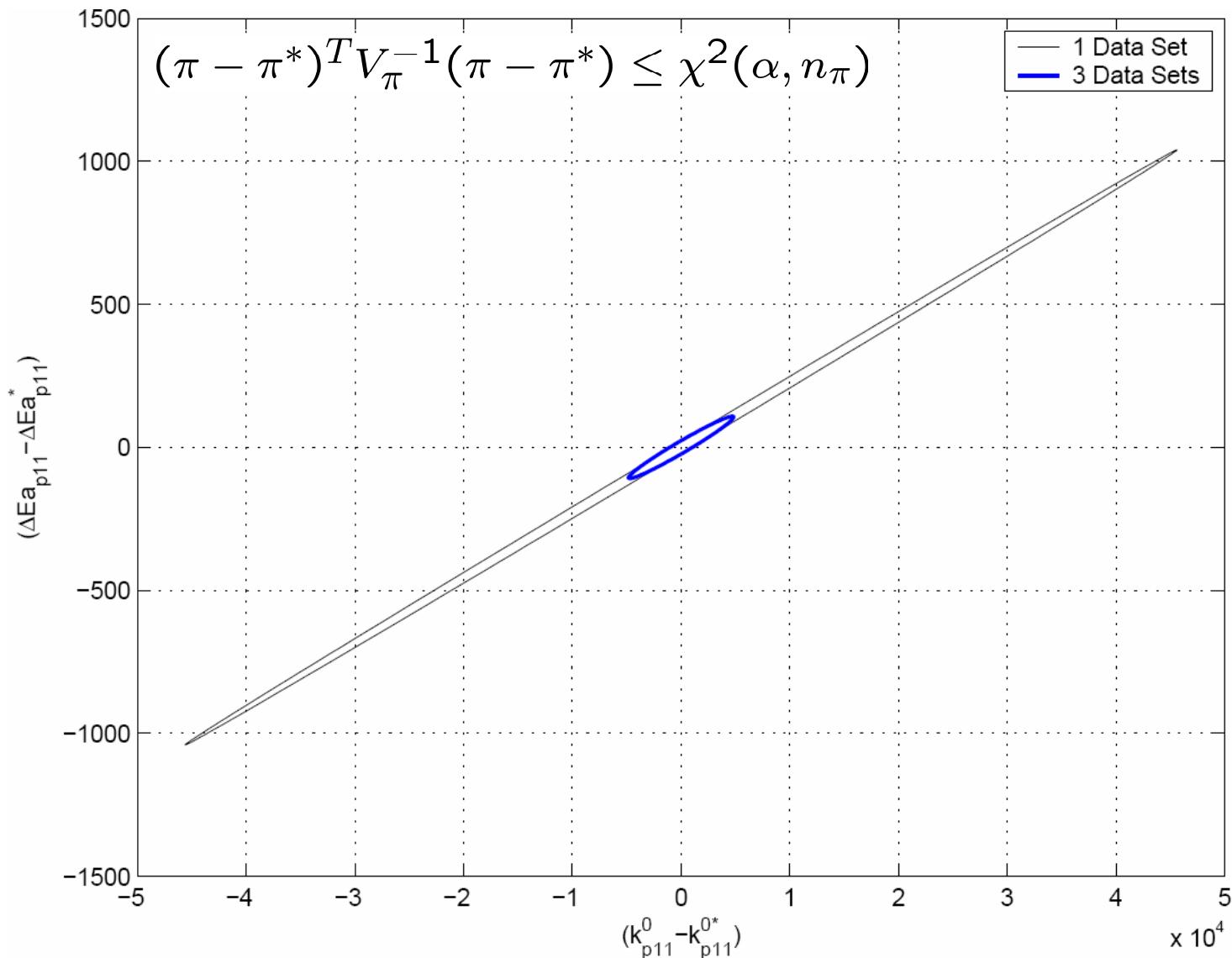
- Already Factored at Solution

- Cheap Sensitivity Calculations

- Confidence Regions  $V_\pi^{-1} \approx \frac{\partial \pi}{\partial y^M}^T V_y^{-1} \frac{\partial \pi}{\partial y^M}$

# Post-Optimal Analysis

## Confidence Regions - Reliability of Parameters





## Summary and Conclusions

# Summary and Conclusions



**Parameter Estimation Fundamental in Science and Engineering**

**Large and Complicated Optimization Problems**

**Robust and Comprehensive Optimization Algorithms -IPOPT-**

**Cope with General Complexity**

**Adapt to Problem Specifics**

**Solve Previously Intractable Estimation Problems**

**Highly Nonlinear, Many Degrees of Freedom**

**Advanced Regression Methods**

**Nonlinear Estimation Problems - Globalization Strategies -**

**Exploit Directions of Negative Curvature *Naturally* - Trust-Region Methods**



# Questions